



Computational Geometry

Chapter 10

Delaunay Triangulation

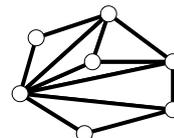
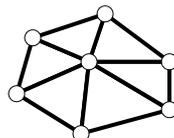
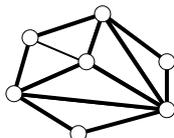
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1



Triangulations

- ❑ A *triangulation* of a set S of points in the plane is a *partition* of the convex hull of the set into triangles whose vertices are the points, and do not contain other points. (Why is there always a triangulation?!)
- ❑ An alternative definition: A maximal collection of line-segments inside $CH(S)$ whose endpoints are points of S . (These segments form the triangles.)
- ❑ There are an exponential number of triangulations of a point set. Best known bound: $O(59^n)$, where n is the number of points [Santos and Seidel, 2003]. Hot update (June 2006): $O(43^n)$ [Sharir and Welzl, 2006].



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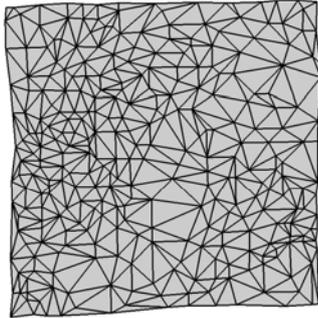
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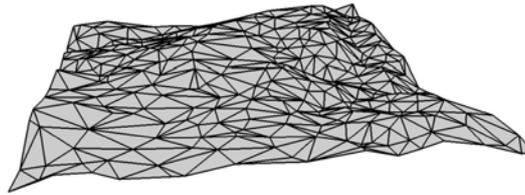


Motivation

- ❑ Assume a height value is associated with each point.
- ❑ A triangulation of the points defines a *piecewise-linear* surface of triangular patches.



2D



3D

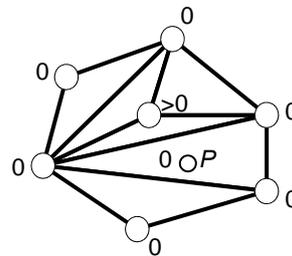
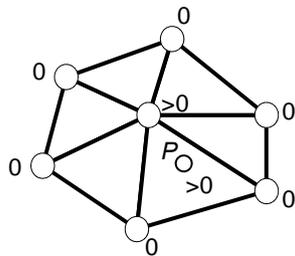
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3



Piecewise-Linear Interpolation

- ❑ The height of a point P inside a triangle is determined by the height of the triangle vertices, and the location of P .
- ❑ The result depends on the triangulation.



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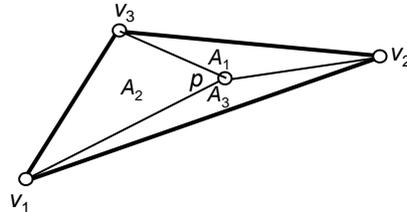
4





Barycentric Coordinates

- Any point inside a triangle can be expressed *uniquely* as a *convex* combination of the triangle vertices:



$$p = \alpha_1 v_1 + \alpha_2 v_2 + \alpha_3 v_3$$

$$\alpha_i = \frac{A_i}{A_1 + A_2 + A_3} \quad \text{for } 1 \leq i \leq 3$$

$$\alpha_i \geq 0, \quad \alpha_1 + \alpha_2 + \alpha_3 = 1$$



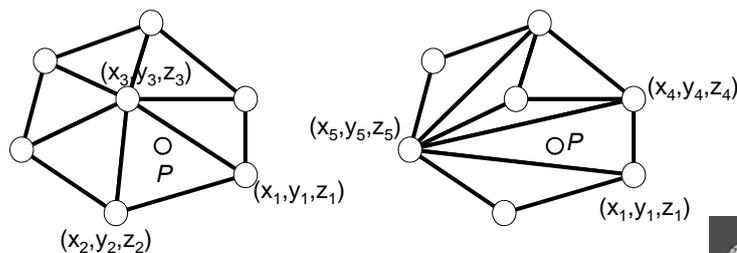
(back to) Piecewise-Linear Interpolation

$$\alpha_1 x_1 + \alpha_2 x_2 + \alpha_3 x_3 = x_p$$

$$\alpha_1 y_1 + \alpha_2 y_2 + \alpha_3 y_3 = y_p$$

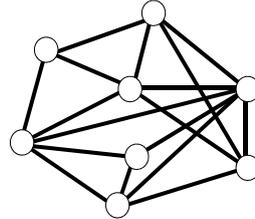
$$\alpha_1 z_1 + \alpha_2 z_2 + \alpha_3 z_3 - z_p = 0$$

$$\alpha_1 + \alpha_2 + \alpha_3 = 1$$



An $O(n^3)$ -Time Triangulation Algorithm

- Repeat
 - Select two sites.
 - If the edge connecting them does not intersect previously kept edges, keep it.
- Until all faces are triangles.
- Question: Why $O(n^3)$ time?
- Question: Why is the algorithm guaranteed to stop before running out of edges?
- Answer: Because every nontriangular face has a diagonal that was not processed yet. (Why?!)



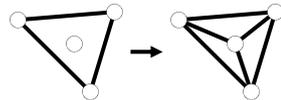
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7

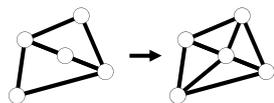


An $O(n \log n)$ -Time Triangulation Algorithm

- Construct the convex hull of the points, and connect one arbitrary vertex to all others.
- Insert the other sites one after the other...
- Two possibilities:
 - Point inside a triangle:
One triangle becomes three.
 - Point on an edge:
Two triangles become four.



- Point on an edge:
Two triangles become four.



Question:
Why $O(n \log n)$ time?

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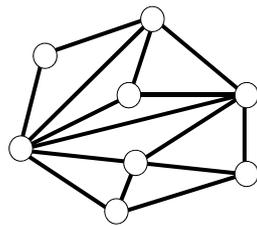
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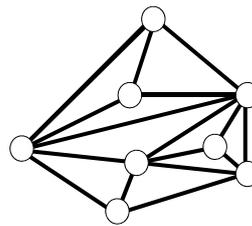
Number of Triangles

- The number of triangles t in a triangulation of n points depends on the number of vertices h on the convex hull: $t = (h-2) + 2(n-h) = 2n-h-2$.



$$h = 6 \rightarrow t = 8$$

$$n = 8$$



$$h = 5 \rightarrow t = 9$$

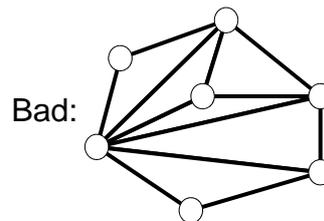
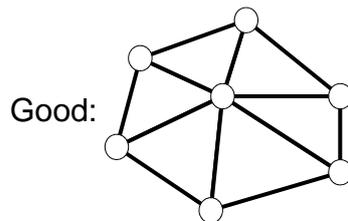
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9



Quality Triangulations

- Consider a triangulation T .
- Let $\alpha(T) = (\alpha_1, \alpha_2, \dots, \alpha_{3t})$ be the vector of angles in the triangulation T sorted in increasing order.
- A triangulation T_1 is "better" than T_2 if $\alpha(T_1) > \alpha(T_2)$ in a lexicographically order.
- The **Delaunay triangulation** is the "best" (avoiding, long skinny triangles, as much as possible).



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10





Thales's Theorem

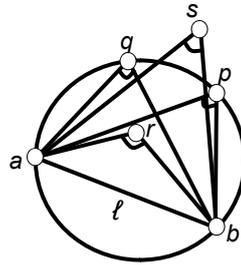
□ Theorem:

Let C be a circle, and ℓ a line intersecting C at the points a and b . Let p , q , r , and s be points lying on the same side of ℓ , where p and q are on C , r inside C , and s outside C . Then:

$$\angle arb > \angle apb = \angle aqb > \angle asb$$

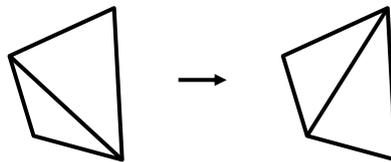
□ Proof omitted.

(Thales proved the theorem directly; one can deduce it from the sine theorem.)



Improving a Triangulation

- In any convex quadrangle, an *edge flip* is possible. (Why? Why isn't it possible in a concave quadrangle?)
- Claim: If this flip *improves* the triangulation locally, it also improves the global triangulation. (Why?)



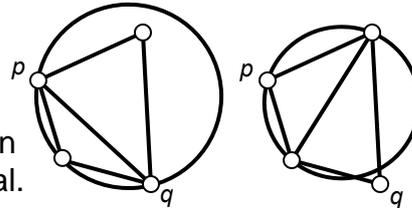
- If an edge flip improves the triangulation (locally and hence globally), the original edge is called *illegal*.





Illegal Edges

- ❑ **Lemma:** An edge pq is illegal iff any of its opposite vertices is inside the circle defined by the other three vertices.
- ❑ **Proof:** By Thales's theorem.
- ❑ Moreover, a convex quadrangle in general position has exactly one legal diagonal.
- ❑ **Theorem:** A Delaunay triangulation does not contain illegal edges. (Otherwise it can be improved locally.)
- ❑ **Corollary:** A triangle is Delaunay iff the circle through its vertices is empty of other sites.
- ❑ **Observation:** The Delaunay triangulation is not unique if more than three sites are cocircular.



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An $\Theta(n^4)$ -Time Delaunay Triangulation

- ❑ For all triples of sites pqr :
 - If the circle through p, q, r does not contain any other site, keep the triangle Δpqr .
- ❑ Complexity: $\Theta(n^3)$ triples, $\Theta(n)$ work per triple;
Total: $\Theta(n^4)$ time.

(Space complexity: $\Theta(n)$.)

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14





The In-Circle Test

Theorem: If a, b, c, d form a CCW convex polygon, then d lies in the circle determined by a, b , and c iff:

$$\det \begin{pmatrix} a_x & a_y & a_x^2 + a_y^2 & 1 \\ b_x & b_y & b_x^2 + b_y^2 & 1 \\ c_x & c_y & c_x^2 + c_y^2 & 1 \\ d_x & d_y & d_x^2 + d_y^2 & 1 \end{pmatrix} > 0$$

Proof:

We prove that equality holds if the points are cocircular.

There exists a center q and radius r such that: $(a_x - q_x)^2 + (a_y - q_y)^2 = r^2$

Similarly for b, c, d .

In vector notation:

$$\begin{pmatrix} a_x^2 + a_y^2 \\ b_x^2 + b_y^2 \\ c_x^2 + c_y^2 \\ d_x^2 + d_y^2 \end{pmatrix} - 2q_x \begin{pmatrix} a_x \\ b_x \\ c_x \\ d_x \end{pmatrix} - 2q_y \begin{pmatrix} a_y \\ b_y \\ c_y \\ d_y \end{pmatrix} + (q_x^2 + q_y^2 - r^2) \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} = 0$$

So these four vectors are linearly dependent, and hence their determinant vanishes.

Corollary: $d \in \circ(a, b, c)$ iff $b \in \circ(a, c, d)$ iff $c \in \circ(b, a, d)$ iff $a \in \circ(b, c, d)$.

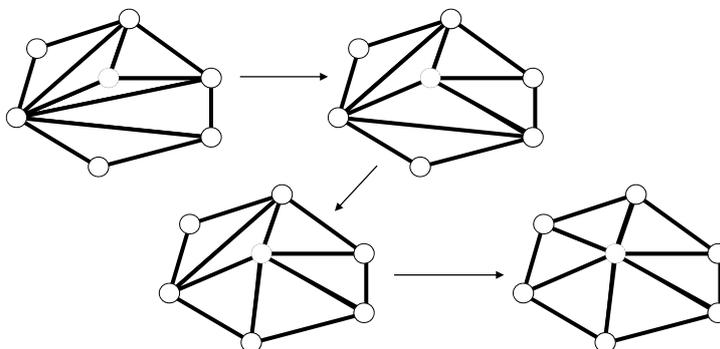
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15



Naive Delaunay Algorithm

- Start with an arbitrary triangulation.
- Flip any illegal edge until no more exist.



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16





Naive Delaunay Algorithm (cont.)

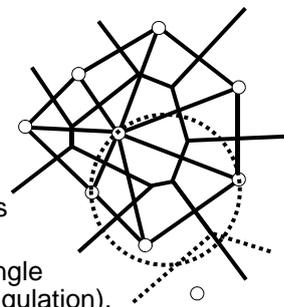
- ❑ Question: Why does the algorithm terminate?
- ❑ Answer: Because every flip increases the vector angle, and there are finitely-many such vectors.
- ❑ However, this algorithm is in practice very slow.

- ❑ Question: Why does the algorithm converge to the optimum triangulation?
- ❑ Answer: Because there are no local maxima (proof deferred).



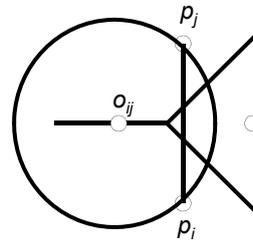
Delaunay Triangulation by Duality

- ❑ Draw the Delaunay graph (the dual graph of the Voronoi diagram) by connecting each pair of neighboring sites in the Voronoi diagram.
- ❑ If no four points are cocircular, then all faces in the Delaunay graph are triangles.
- ❑ General position assumption: There are no four cocircular points.
- ❑ We need to prove:
 - Correctness of this duality. I.e., drawing the Delaunay graph with straight segments does not cause any segment intersection.
 - This triangulation indeed maximizes the angle vector (and, hence, it is the Delaunay triangulation).
- ❑ **Corollary:** The Delaunay triangulation (DT) of n points can be computed in $O(n \log n)$ time.



Proof of Planarity of Delaunay Triangulation

- Let S be a set of sites, and let $DT(S)$ be the dual graph of $VD(S)$.
- Let $p_i p_j$ be an edge of $DT(S)$.
It is so because cells of p_i and p_j in $VD(S)$ are neighbors in $VD(S)$. Hence, there exists an **empty** circle passing through p_i, p_j and whose center o_{ij} is on their bisector (the edge of $VD(S)$ separating between the cells of p_i and p_j).
- Assume for contradiction that $p_i p_j$ intersects another edge $p_k p_l$ in $DT(S)$.
- Observe the possible interactions between the triangles $\Delta o_{ij} p_i p_j$ and $\Delta o_{kl} p_k p_l \dots$ (next slide)



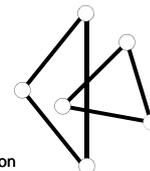
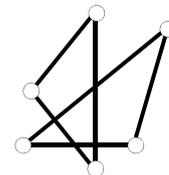
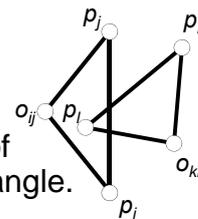
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19



Planarity Proof (cont.)

- Case A (one triangle contains a yellow vertex of the other triangle):
Impossible, since the circumscribing circle of the first triangle is empty, hence also the triangle.
- Case B (no triangle contains a vertex of the other triangle):
Cannot avoid an intersection of a pair of white edges, which is impossible, because the white edges are fully contained in **disjoint** Voronoi cells.
- Case C (one triangle contains a green vertex of the other triangle) is possible.
Question: Why isn't it a contradiction?



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20



Delaunay Triangulation: Main Property

□ Theorem:

Let S be a set of points in the plane. Then,

- (i) $p_i, p_j, p_k \in S$ are vertices of a triangle (face) of $DT(S)$
 - \leftrightarrow The circle passing through p_i, p_j, p_k is empty;
- (ii) $\overline{p_i, p_j}$ (for $p_i, p_j \in S$) is an edge of $DT(S)$
 - \leftrightarrow There exists an empty circle passing through p_i, p_j .

□ **Proof:** Dualize the Voronoi-diagram theorem.

□ Corollary:

A triangulation $T(S)$ is $DT(S)$

- \leftrightarrow Every circumscribing circle of a triangle $\Delta \in T(S)$ is empty.

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21



Wrapping Up

□ Theorem:

Let S be a set of points in the plane, and let $T(S)$ be a triangulation of S . Then,

$T(S) = DT(S) \leftrightarrow T(S)$ is legal.

□ **Proof:** Follows from the definitions of a legal edge and triangulation. (Exercise!)

□ **Corollary:** $DT(S)$ maximizes the vector angle.

□ Since $DT(S)$ is unique, there is only one legal triangulation, and thus, there are no local maxima in the edge-flip algorithm. Hence, the algorithm converges to $DT(S)$.

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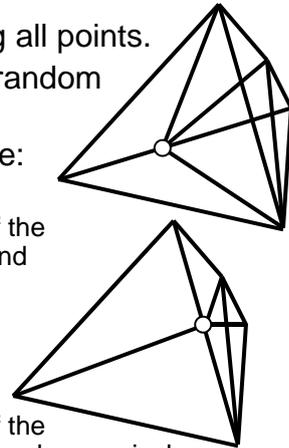
22



An $O(n \log n)$ -Time Delaunay Algorithm

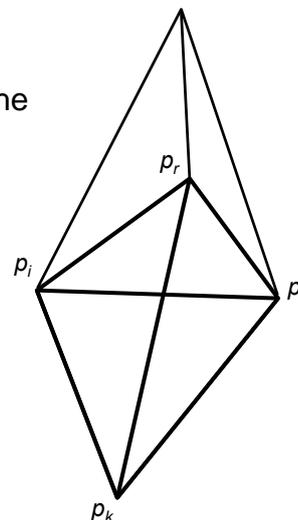
A **Randomized** incremental algorithm:

- ❑ Form a bounding triangle Δ_0 enclosing all points.
- ❑ Add the points one after another in a random order and update the triangulation.
- ❑ If the point is inside an existing triangle:
 - Connect the point to the triangle vertices.
 - Check if a flip can be performed on any of the three triangle edges. If so, flip the edge and check recursively the neighboring edges (opposite to the new point).
- ❑ If the site is on an existing edge:
 - Replace the edge with four new edges.
 - Check if a flip can be performed on any of the opposite edges. If so, flip the edge and check recursively the neighboring edges (opposite to the new point).



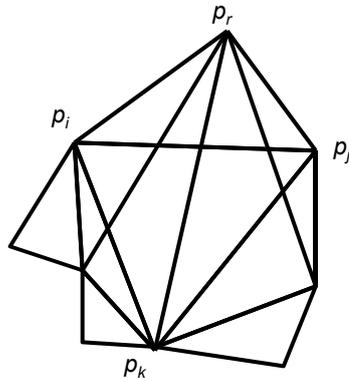
Flipping Edges

- ❑ A new point p_r was added, causing the creation of the edges $p_i p_r$ and $p_j p_r$.
- ❑ The legality of the edge $p_i p_j$ (with opposite vertex) p_k is checked.
- ❑ If $p_i p_j$ is illegal, perform a flip, and recursively check edges $p_i p_k$ and $p_j p_k$, the new edges opposite to p_r .
- ❑ Notice that the recursive call for $p_i p_k$ cannot eliminate the edge $p_r p_k$.
- ❑ **Note:** All edge flips replace edges opposite to the new vertex by edges adjacent to it!





Flipping Edges: Example



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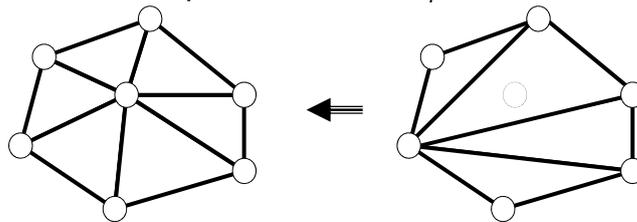
Number of Triangles

□ **Theorem:** The expected number of triangles created in the course of the algorithm (some of which also disappear) is at most $9n+1$.

□ **Proof:**

During the insertion of point p_i , k_i new edges are created: 3 new initial edges, and k_i-3 due to flips. Hence, the number of new triangles is at most $3+2(k_i-3) = 2k_i-3$. (A point on an edge results in $2k_i-4$ triangles.)

□ What is the expected value of k_i ?



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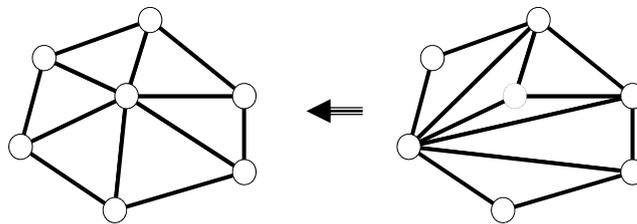
26





Number of Triangles (cont.)

- ❑ Recall that the Voronoi diagram has at most $3N - 6$ edges, where N is the number of vertices.
- ❑ The number of edges in a graph and its dual are identical.
- ❑ Taking into account the initial triangle Δ_0 , after inserting i points, there are at most $3(i+3) - 6 = 3i + 3$ edges.
Three of them belong to Δ_0 , so we are left with at most $3i$ internal edges that are adjacent to the input points.



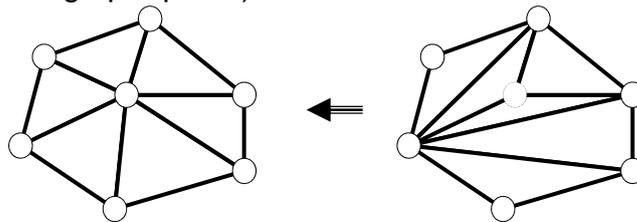
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27



Number of Triangles (cont.)

- ❑ The sum of all vertex degrees is thus at most $2 \cdot 3i = 6i$.
- ❑ On the average, the degree of each vertex is only 6 !
But this is exactly the number of new edges!
- ❑ Hence, the expected number of triangles created in the i th step is at most $E(2k_i - 3) = 2 E(k_i) - 3 = 9$.
- ❑ Therefore, the expected number of triangles created (and possibly destroyed) for n points is $9n + 1$.
(One initial bounding triangle plus 9 triangles on average per point.)



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28





Algorithm Complexity

- ❑ Point location for every point: $O(\log n)$ time (not shown).
- ❑ Flips: $\Theta(n)$ expected time in total (for all steps).
- ❑ Total expected time: $O(n \log n)$.
- ❑ Space: $\Theta(n)$.



Relatives of the Delaunay Triangulation

- ❑ **Euclidean Minimum Spanning Tree (EMST):**
A tree of minimum length connecting all the sites.

- ❑ **Relative Neighborhood Graph (RNG):**
Two sites p, q are connected if

$$d(p, q) \leq \min_{r \in P, r \neq p, q} \max(d(p, r), d(q, r))$$

- ❑ **Gabriel Graph (GG):**
Two sites p, q are connected if the circle whose *diameter* is pq is empty of other sites.

- ❑ **Theorem:** $\text{EMST} \subseteq \text{RNG} \subseteq \text{GG} \subseteq \text{DT}$.



Delaunay Triangulation and Convex Hulls

$z=x^2+y^2$ $z=x^2+y^2$ $z=x^2+y^2$

Project the 2D point set onto the 3D paraboloid → Compute the 3D lower convex hull → Project the 3D facets back to the plane.

The 2D triangulation is Delaunay!

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Proof of Lift-Up Method

- The intersection of a plane with the paraboloid is an ellipse whose projection to the plane is a circle.
- s lies within the circumcircle of p, q, r iff s' lies on the lower side of the plane passing through p', q', r' .

↓

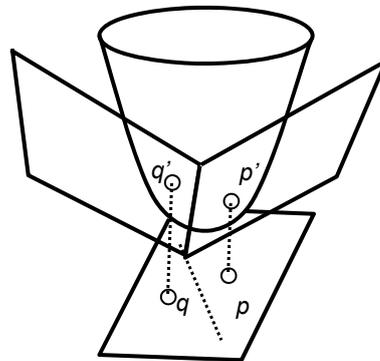
- $p, q, r \in S$ form a Delaunay triangle iff p', q', r' form a face of the convex hull of S' .

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More about Lifting Up

- Given a set S of points in the plane, associate with each point $p=(a,b) \in S$ the plane $z = 2ax+2by-(a^2+b^2)$, which is tangent to the paraboloid at p' , the vertical projection of p onto the paraboloid.



- $VD(S)$ is the vertical projection onto the XY plane of the boundary of the convex polyhedron that is the intersection of the halfspaces above these planes.

