



Computational Geometry

Chapter 3

Polygons and Triangulation

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On the Agenda

- The Art Gallery Problem
- Polygon Triangulation

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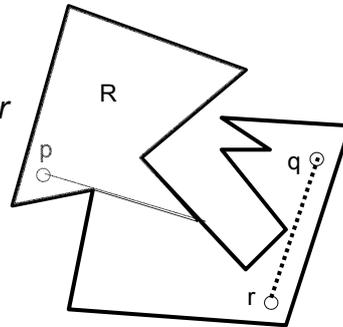
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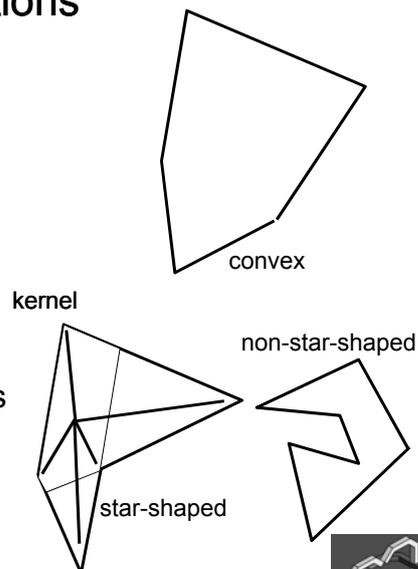
Art Gallery Problem

- Given a simple polygon P , say that two points q and r can see each other if the open segment qr lies entirely within P .
- A point p guards a region $R \subseteq P$ if p sees all points $q \in R$.
- Given a polygon P , what is the minimum number of guards required to guard P , and what are their locations?



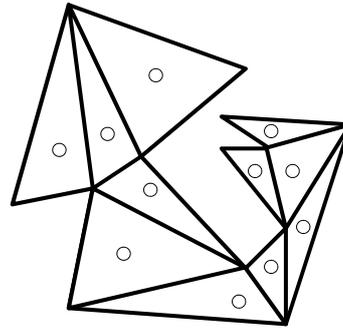
Observations

- The *entire* interior of a convex polygon is visible from *any* interior point. (**Why?**)
- A *star-shaped* polygon requires only one guard located in its *kernel*.



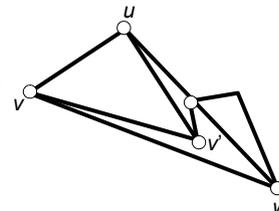
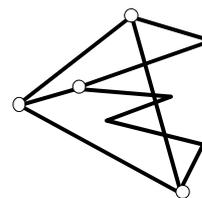
Art Gallery Problem: Easy Upper Bound

- **Theorem** (to be proven later):
Every simple planar polygon with n vertices has a triangulation into $n-2$ triangles.
- $n-2$ guards suffice for an n -gon:
 - Subdivide the polygon into $n-2$ triangles (triangulation).
 - Place one guard in each triangle.



Diagonals in Polygons

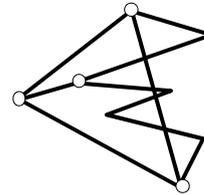
- A *diagonal* of a polygon P is a line segment connecting two vertices, which lies **entirely** within P .
- **Theorem:** Every polygon with $n > 3$ vertices has a diagonal.
- **Proof:** Find the leftmost vertex v . Connect its two neighbors u and w . If this is not a diagonal there must be other vertices inside the triangle uvw . Connect v with the vertex v' **farthest** from the segment uw . This must be a diagonal.
- **Questions:**
 1. Why is $v'v$ a diagonal?
 2. Why not connect v with the leftmost vertex inside uvw ?





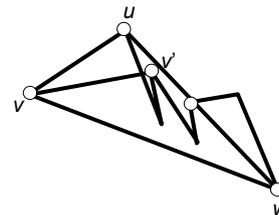
Diagonals in Polygons

□ A *diagonal* of a polygon P is a line segment connecting two vertices, which lies **entirely** within P .



□ **Theorem:** Every polygon with $n > 3$ vertices has a diagonal.

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□ **Questions:**

1. Why is $v'v$ a diagonal?
2. Why not connect v with the leftmost vertex inside uvw ?

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Complexity of Triangulations

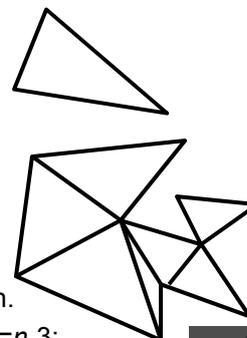
□ **Theorem:** Any triangulation of a simple polygon with n vertices consists of $n-3$ diagonals and $n-2$ triangles.

□ **Proof:** By induction on n :

■ **Basis:** A triangle ($n=3$) has a triangulation (itself) with no diagonals and one triangle.

■ **Inductive step:**

1. For an n -vertex polygon, construct a diagonal dividing the polygon into two polygons with n_1 and n_2 vertices such that $n_1 + n_2 - 2 = n$. (Why “-2”?)
2. Triangulate the two parts of the polygon.
3. Diagonals: $(n_1 - 3) + (n_2 - 3) + 1 = (n_1 + n_2 - 2) - 3 = n - 3$;
Triangles: $(n_1 - 2) + (n_2 - 2) = (n_1 + n_2 - 2) - 2 = n - 2$.



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$\Theta(n^2)$ -Time Polygon Triangulation

- ❑ Algorithm:
 1. Input: A simple n -gon.
 2. Find a diagonal.
 3. Call the algorithm recursively for the two subpolygons.

- ❑ Analysis: $T(n) = O(n) + \max_{n_1+n_2=n+2} (T(n_1) + T(n_2))$

diagonal
recursion

- ❑ Solution: $T(n) = \Theta(n^2)$

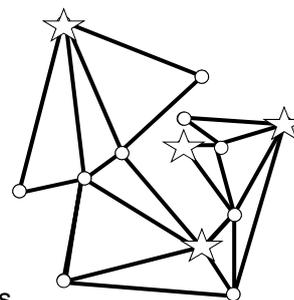
- ❑ Space: $\Theta(n)$



Art Gallery Problem: Upper Bound

- ❑ Color the vertices of the (triangulated) polygon with three colors such that there is no edge between two vertices with the same color.
- ❑ **Question:** Why is this possible?
 (Hint: The dual of any triangulation is a tree with vertex degree at most 3. Full proof later.)
- ❑ Corollary: All triangles are 3-colored.
- ❑ Pick the color that is the least used. This color is used in at most $\lfloor n/3 \rfloor$ vertices.
- ❑ Place a guard on each vertex with this color.
 Due to the corollary all the triangles are guarded!

- ❑ \Rightarrow New upper bound: $\lfloor n/3 \rfloor$





3-Coloring

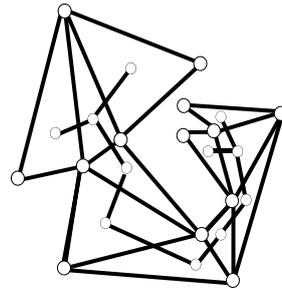
□ **Theorem:** Every triangulated polygon can be 3-colored.

□ **Proof:** Consider the *dual* graph.

- Since every diagonal disconnects the polygon, the dual graph is a **tree**.
- Since every node in the graph is the dual of a triangle, its degree is ≤ 3 .
- Since any tree has a leaf, any triangulation has an ear (a triangle containing two polygon edges).
- Finally, by induction on n :

Basis: Trivial if $n=3$.

Induction: Cut off an ear. 3-color the remaining $(n-1)$ -gon. Color the n th vertex with the third color different from the two on its supporting edge.



3-Coloring

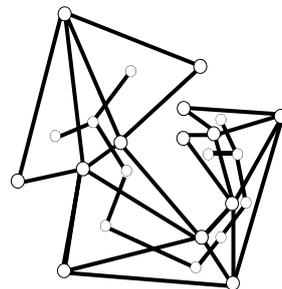
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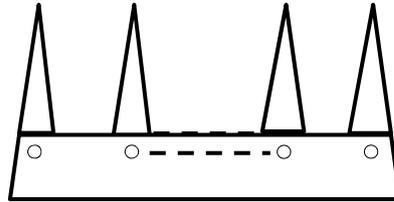
Induction: Cut off an ear. 3-color the remaining $(n-1)$ -gon. Color the n th vertex with the third color different from the two on its supporting edge.





A Matching Lower Bound

- ❑ Fact: There exists a polygon with n vertices, for which $n/3$ guards are necessary.



- ❑ Therefore, $\lfloor n/3 \rfloor$ guards are needed in the worst case.

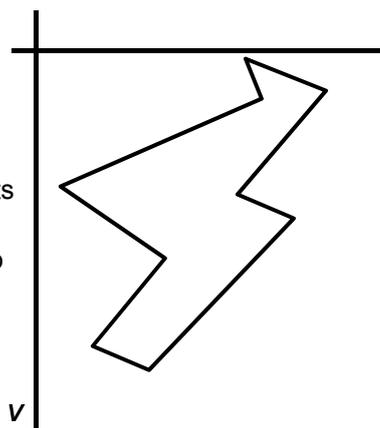


$O(n \log n)$ -Time Polygon Triangulation

- ❑ A simple polygon is called *monotone* with respect to a direction v if for any line ℓ perpendicular to v , the intersection of the polygon with ℓ is connected.
- ❑ A polygon is called *monotone* if there exists any such direction v .
- ❑ A polygon that is monotone with respect to the x - (or y -) axis is called *x - (or y -) monotone*.

Question 1: How can we check in $O(n)$ time whether a polygon is y -monotone?

Question 2: What is a polygon that is monotone with respect to **all** directions?



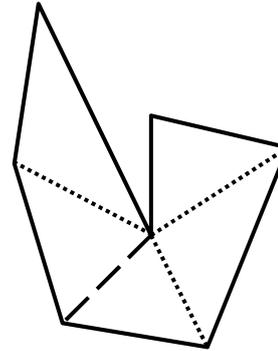
y -monotone but not x -monotone polygon





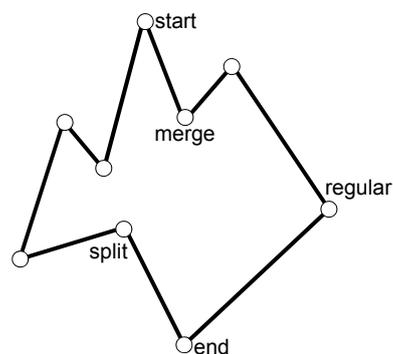
Triangulation Algorithm – cont.

- 1) Partition the polygon into y -monotone pieces (“חתיכות מונוטוניות”).
- 2) Triangulate each y -monotone piece separately.



y -Monotone Polygons

- Classifying polygon vertices:
 - A *start* (resp., *end*) vertex is a vertex whose interior angle is less than π and its two neighboring vertices both lie below (resp., above) it.
 - A *split* (resp., *merge*) vertex is a vertex whose interior angle is greater than π and its two neighboring vertices both lie below (resp., above) it.
 - All other vertices are *regular*.

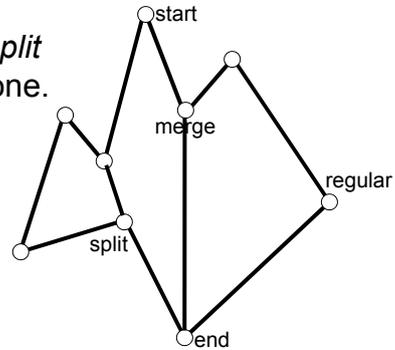




y-Monotone Polygons (cont.)

□ **Theorem:** A polygon without *split* and *merge* vertices is *y*-monotone.

□ **Proof:** Since there are only start/end/regular vertices, the polygon must consist of two *y*-monotone chains.

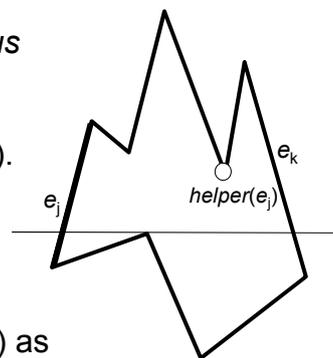


□ To partition a polygon to monotone pieces, eliminate split (merge) vertices by adding diagonals upward (downward) from the vertex. Naturally, the diagonals **must not** intersect!



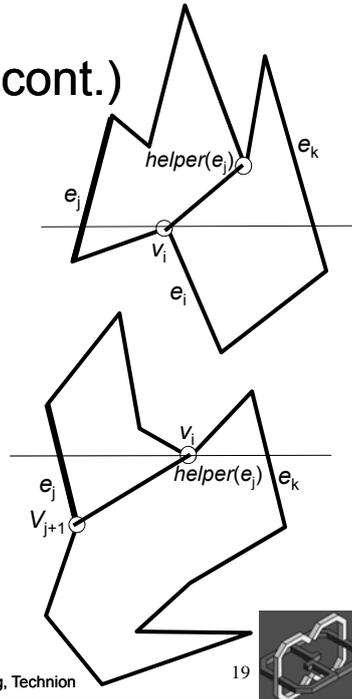
Monotone Partitioning

- Classify all vertices.
- Sweep the polygon from top to bottom.
- Maintain the edges intersected by the sweep line in a *sweep line status* (SLS sorted by *x* coordinates).
- Maintain vertex events in an event queue (EQ sorted by *y* coordinates). All events are known in advance!
- Eliminate split/merge vertices by connecting them to other vertices (to be explained later).
- For each edge e , define $helper(e)$ as the lowest vertex (seen so far) above the sweep line **visible** to the right of the edge.
- $helper(e)$ is initialized by the upper endpoint of e .



Monotone Partitioning (cont.)

- ❑ A split vertex may be connected to the helper vertex of the edge immediately to its left.
- ❑ However, a merge vertex should be connected to a vertex which has not been processed yet!
- ❑ Clever idea: Every merge vertex v is the helper of some edge e , so that v will be resolved either
 - when e disappears;
 - when v ceases to be the helper of e .
 It will be the last time v can be resolved!



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Monotone Partitioning Algorithm

- ❑ Input: A polygon P , given as a list of vertices ordered counterclockwise. The edge e_i immediately follows the vertex v_i .
- ❑ Construct EQ containing the vertices of P sorted by their y -coordinates. (In case two or more vertices have the same y -coordinate, the vertex with the smaller x -coordinate has a higher priority.)
- ❑ Initialize SLS to be empty.
- ❑ While EQ is not empty:
 - Pop vertex v ;
 - Handle v .
 (No new events are generated during execution.)
- ❑ Idea: No split/merge vertex remains unhandled!

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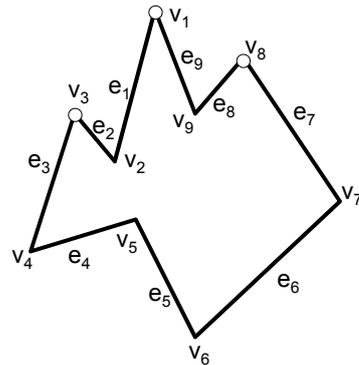
Monotone Partitioning

□ Handling a *start* vertex (v_i):

- Add e_i to SLS
- $helper(e_i) := v_i$

□ Implementation detail:

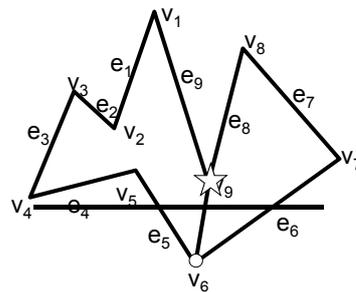
Only “left” edges (for which the polygon is on the right) need a helper and are thus kept in the status.



Monotone Partitioning

□ Handling an *end* vertex (v_i):

- If $helper(e_{i-1})$ is a merge vertex, then connect v_i to $helper(e_{i-1})$ (Why?!)
- Remove e_{i-1} from SLS

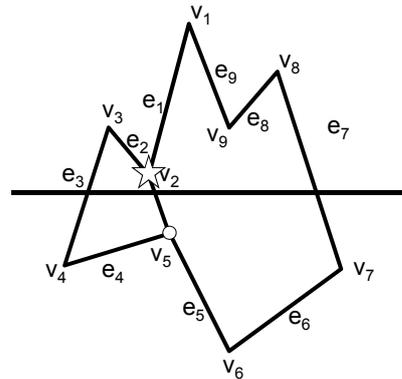




Monotone Partitioning

□ Handling a *split* vertex (v_i):

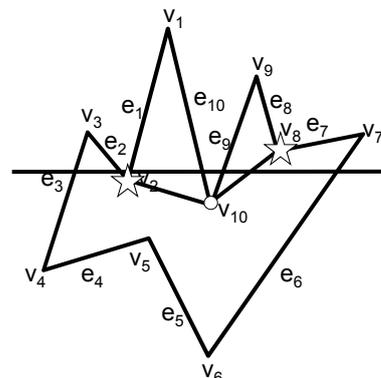
- Find in SLS the edge e_j directly to the left of v_i
- Connect v_i to $helper(e_j)$
- $helper(e_j) := v_i$
- Insert e_i into SLS
- $helper(e_i) := v_i$



Monotone Partitioning

□ Handling a *merge* vertex (v_i):

- If $helper(e_{i-1})$ is a merge vertex, then connect v_i to $helper(e_{i-1})$
- Remove e_{i-1} from SLS
- Find in SLS the edge e_j directly to the left of v_i
- If $helper(e_j)$ is a merge vertex, then connect v_i to $helper(e_j)$
- $helper(e_j) := v_i$

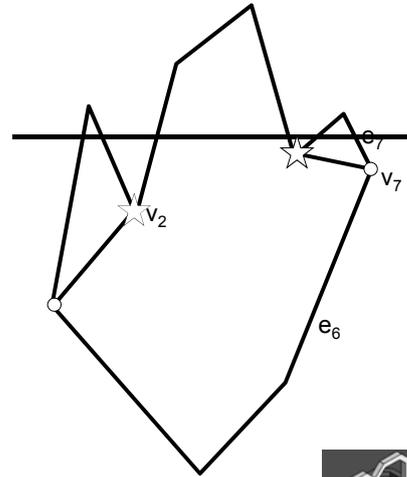




Monotone Partitioning

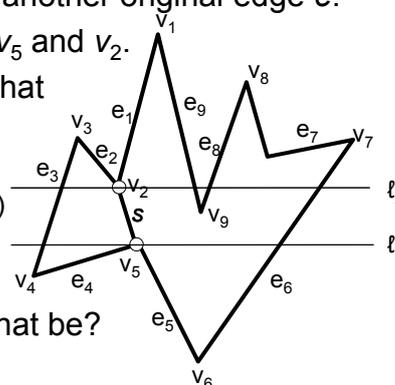
□ Handling a *regular* vertex (v_i):

- If the polygon's interior lies to the left of v_i then:
 - Find in SLS the edge e_j directly to the left of v_i
 - If $helper(e_j)$ is a merge vertex, then connect v_i to $helper(e_j)$
 - $helper(e_j) := v_i$
- Else:
 - If $helper(e_{i-1})$ is a merge vertex, then connect v_i to $helper(e_{i-1})$
 - Remove e_{i-1} from SLS
 - Insert e_i into SLS
 - $helper(e_i) := v_i$



Proof of Correctness: Split Vertices

- Assume that the split vertex v_5 was connected to v_2 .
- Assume that $s=v_5v_2$ intersects another original edge e .
- Draw horizontal lines through v_5 and v_2 .
- Where can the endpoint of e , that is to the left of s , be?
 - Below ℓ_1 : Impossible. (Why?)
 - Between ℓ_1 and ℓ_2 : Ditto. (Why?)
 - Above ℓ_2 : Ditto. (Why?)
- Now assume that s intersects another diagonal. Why can't that be?
- Conclusion:
Split events are resolved correctly.





Proof of Correctness (cont.)

- Merge vertices: Exercise.

- Complete the details of the proof as an exercise.



Triangulating a y -monotone Polygon

In Theory

- Sweep the polygon from top to bottom.
- Greedily triangulate anything possible above the sweep line, and then forget about this region.
 - When we process a vertex v , the unhandled region above it always has a simple structure: Two y -monotone (left and right) chains, each containing at least one edge. If a chain consists of two or more edges, it is *reflex*, and the other chain consists of a single edge whose bottom endpoint has not been handled yet.
 - Each diagonal is added in $O(1)$ time.

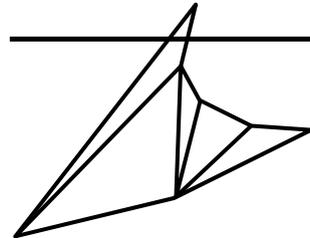




Triangulating a Y-monotone Polygon

In Practice

- ❑ Continue sweeping while one chain contains only one edge, while the other edge is *concave*.
- ❑ When a “convex edge” appears in the concave chain, triangulate as much as possible by connecting the new vertices to all visible vertices of the concave chain.
- ❑ When the edge in the other chain terminates, connect it to all the vertices of the concave chain using a “fan”.
- ❑ Time complexity: $O(k)$, where k is the complexity of the polygon.



Question: Why?!

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Total Time-Complexity Analysis

- ❑ Partitioning the polygon into monotone pieces: $O(n \log n)$
(every vertex event is handled in $O(\log n)$ time)
 - ❑ Triangulating all the monotone pieces: $\Theta(n)$
(every vertex event is handled in $\Theta(1)$ time)
-
- Total: $O(n \log n)$

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Historical Perspective

- $O(n^2)$: Diagonal insertion
- $O(n \log n)$: Lee and Preparata
(Monotone decomposition, 1977)
Avis and Toussaint (1981)
Chazelle (1982)

Optimal??

- $O(n \log \log n)$: Tarjan and Van Wyk (1988)
- $O(n \log^* n)$: **Randomized:**
Clarkson, Tarjan, and Van Wyk (1989)
Seidel (Trapezoidal decomposition, 1991)
Devillers (1992)
- $\Theta(n)$: **Optimal** (yet deterministic):
Chazelle (1991)

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