Computational Geometry

Chapter 3

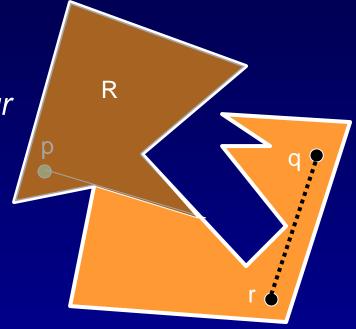
Polygons and Triangulation

On the Agenda

- ☐ The Art Gallery Problem
- Polygon Triangulation

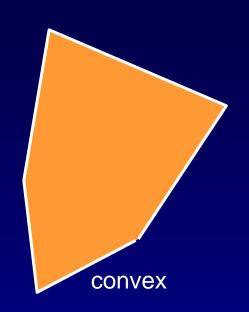
Art Gallery Problem

- ☐ Given a simple polygon *P*, say that two points *q* and *r* can see each other if the open segment *qr* lies entirely within *P*.
- A point p guards a region R ⊆ P if p sees all points q∈R.
- ☐ Given a polygon *P*, what is the minimum number of guards required to guard *P*, and what are their locations?

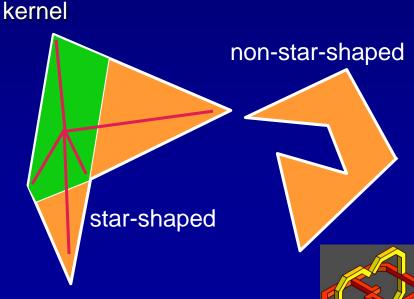


Observations

□ The entire interior of a convex polygon is visible from any interior point. (Why?)

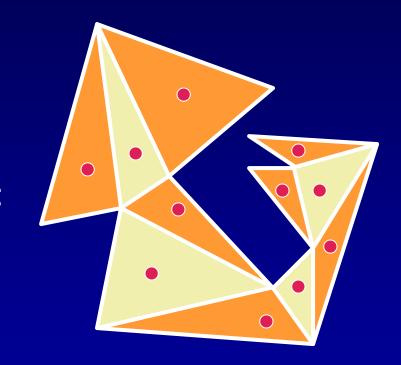


A star-shaped polygon requires only one guard located in its kernel.



Art Gallery Problem: Easy Upper Bound

- Theorem (to be proven later): Every simple planar polygon with n vertices has a triangulation into n-2 triangles.
- n-2 guards suffice for an n-gon:
 - Subdivide the polygon into *n*-2 triangles (triangulation).
 - Place one guard in each triangle.



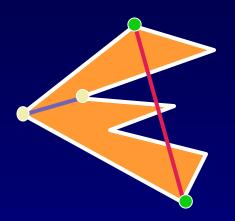
Diagonals in Polygons

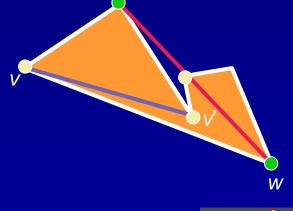
A *diagonal* of a polygon *P* is a line segment connecting two vertices, which lies **entirely** within *P*.

- ☐ **Theorem:** Every polygon with n>3 vertices has a diagonal.
- Proof: Find the leftmost vertex v. Connect its two neighbors u and w. If this is not a diagonal there must be other vertices inside the triangle uvw. Connect v to the vertex v' farthest from the segment uw. This must be a diagonal.



- 1. Why is v'v a diagonal?
- 2. Why not connect *v* with the leftmost vertex inside *uvw*?







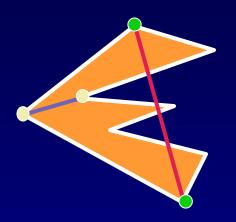
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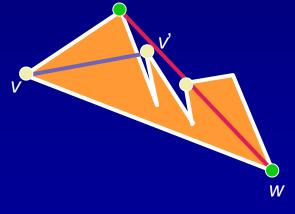
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Complexity of Triangulations

- Theorem: Any triangulation of a simple polygon with n vertices consists of n-3 diagonals and n-2 triangles.
- **Proof:** By induction on *n*:
 - Basis: A triangle (*n*=3) has a triangulation (itself) with no diagonals and one triangle.
 - Inductive step:
 - 1. For an n-vertex polygon, construct a diagonal dividing the polygon into two polygons with n_1 and n_2 vertices such that $n_1+n_2-2=n$. (Why "-2"?)
 - 2. Triangulate the two parts of the polygon.
 - 3. Diagonals: $(n_1-3)+(n_2-3)+1=(n_1+n_2-2)-3=n-3$; Triangles: $(n_1-2)+(n_2-2)=(n_1+n_2-2)-2=n-2$.

Center for Graphics and Geometric Computing, Technion

$\Theta(n^2)$ -Time Polygon Triangulation

- Algorithm:
 - 1. Input: A simple *n*-gon.
 - 2. Find a diagonal.
 - 3. Call the algorithm recursively for the two subpolygons.
- Analysis: $T(n) = O(n) + \max_{n_1 + n_2 = n+2} (T(n_1) + T(n_2))$ diagonal recursion

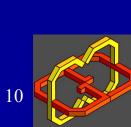
$$T(3), T(4) = \Theta(1)$$

- □ Solution: $T(n) = \Theta(n^2)$ time
- \square Space: $\Theta(n)$



Art Gallery Problem: Upper Bound

- Color the vertices of the (triangulated) polygon with three colors such that there is no edge between two vertices with the same color.
- Question: Why is this possible? (Hint: The dual of any triangulation is a tree with vertex degree at most 3. Full proof later.)
- Corollary: All triangles are 3-colored.
- Pick the color that is the least used. This color is used in at most n/3 vertices.
- Place a guard on each vertex with this color. Due to the corollary all the triangles are guarded!
- $\square \Rightarrow$ New upper bound: $\lfloor n/3 \rfloor$

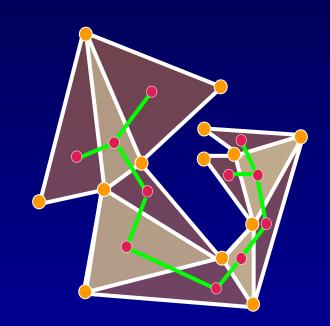


3-Coloring

- Theorem: Every triangulated polygon can be 3-colored.
- **Proof:** Consider the *dual* graph.
 - Since every diagonal disconnects the polygon, the dual graph is a tree.
 - Since every node in the graph is the dual of a triangle, its degree is ≤ 3.
 - Since any tree has a leaf, any triangulation has an ear (a triangle containing two polygon edges).
 - Finally, by induction on *n*:

Basis: Trivial if *n*=3.

Induction: Cut off an ear. 3-color the remaining (n-1)-gon. Color the *n*th vertex with the third color different from the two on its supporting edge.

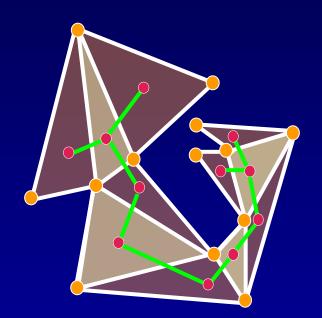


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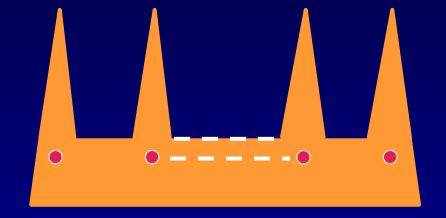
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A Matching Lower Bound

□ Fact: There exists a polygon with n vertices, for which n/3 guards are necessary.



☐ Therefore, [n/3] guards are needed in the worst case.

$O(n \log n)$ -Time Polygon Triangulation

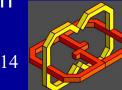
- A simple polygon is called *monotone* with respect to a direction *v* if for any line *l* perpendicular to *v*, the intersection of the polygon with \ell\ is connected.
- A polygon is called *monotone* if there exists any such direction v.
- A polygon that is monotone with respect to the x- (or y-) axis is called x- (or y-) monotone.

Question 1: How can we check in O(n)time whether a polygon is *y*-monotone?

Question 2: What is a polygon that is monotone with respect to all directions?

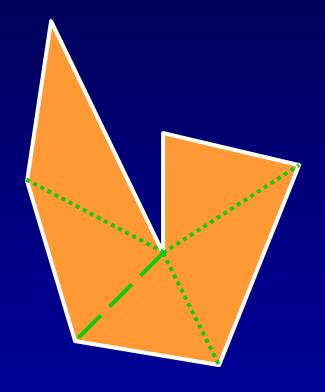


y-monotone but not x-monotone polygon



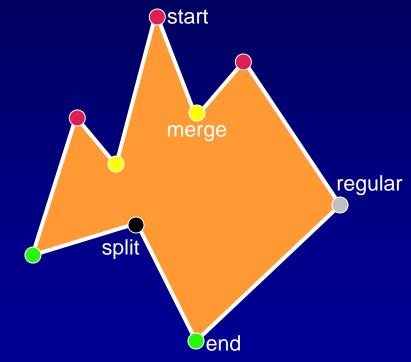
Triangulation Algorithm – cont.

- Partition the polygon into y-monotone pieces ("חתיכות מונוטוניות").
- 2) Triangulate each y-monotone piece separately.



y-Monotone Polygons

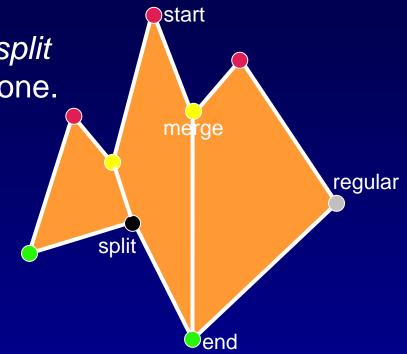
- Classifying polygon vertices:
 - A start (resp., end) vertex is a vertex whose interior angle is less than π and its two neighboring vertices both lie below (resp., above) it.
 - A split (resp., merge) vertex is a vertex whose interior angle is greater than π and its two neighboring vertices both lie below (resp., above) it.
 - All other vertices are regular.



y-Monotone Polygons (cont.)

☐ **Theorem:** A polygon without *split* and *merge* vertices is *y*-monotone.

□ Proof: Since there are only start/end/regular vertices, the polygon must consist of two y-monotone chains.



□ To partition a polygon into monotone pieces, eliminate split (merge) vertices by adding diagonals upward (downward) from the vertex.
Naturally, the diagonals must not intersect!

Monotone Partitioning

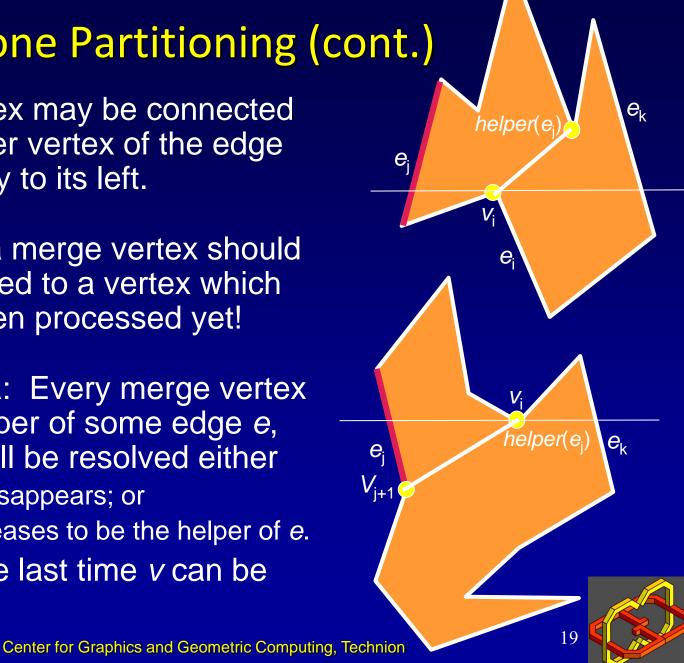
- Classify all vertices.
- Sweep the polygon from top to bottom.
- Maintain the edges intersected by the sweep line in a sweep line status (SLS sorted by x coordinates).
- Maintain vertex events in an event queue (EQ sorted by y coordinates). events are known in advance!
- Eliminate split/merge vertices by connecting them to other vertices be explained later).
- * For each edge e, define helper(e) as the lowest vertex (seen so far) above the sweep line, which is visible to the edge on its right side.
- helper(e) is initialized by the upper endpoint of e.

Monotone Partitioning (cont.)

A split vertex may be connected to the helper vertex of the edge immediately to its left.

- However, a merge vertex should be connected to a vertex which has not been processed yet!
- Clever idea: Every merge vertex v is the helper of some edge e, so that v will be resolved either
 - when e disappears; or
 - when *v* ceases to be the helper of *e*.

It will be the last time v can be resolved!



Monotone Partitioning Algorithm

- Input: A polygon P, given as a list of vertices ordered counterclockwise. The edge e_i immediately follows the vertex v_i .
- Construct EQ containing the vertices of P sorted by their y-coordinates. (In case two or more vertices have the same y-coordinate, the vertex with the smaller x-coordinate has a higher priority.)
- Initialize SLS to be empty.
- While EQ is not empty:
 - Pop vertex *v*;
 - Handle *v*.

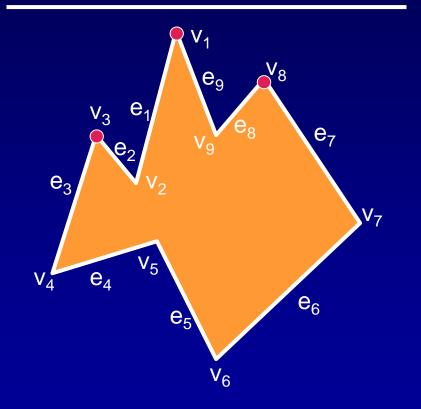
(No new events are generated during execution.)

Idea: No split/merge vertex remains unhandled!



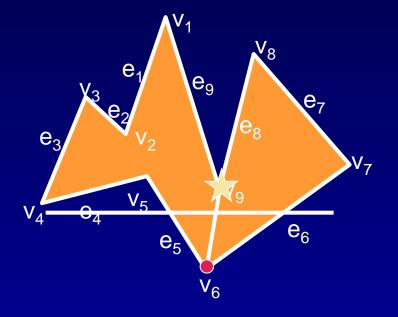
Start Vertices

- ☐ Handling a *start* vertex (v_i):
 - Add *e*_i to SLS
 - \blacksquare helper(e_i) := v_i
- Implementation detail: Only "left" edges (for which the polygon is on the right) need a helper and are thus kept in the status.



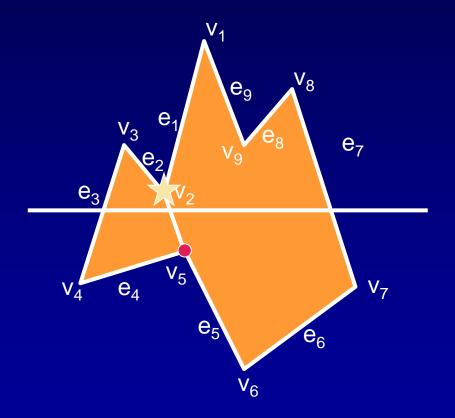
End Vertices

- ☐ Handling an *end* vertex (v_i):
 - If helper(e_{i-1}) is a merge vertex, then connect v_i to helper(e_{i-1}) (Why?!)
 - Remove e_{i-1} from SLS



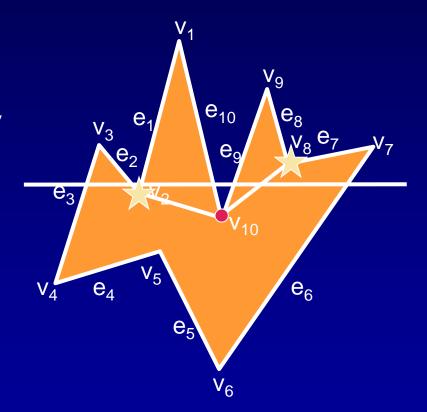
Split Vertices

- \square Handling a *split* vertex (v_i):
 - Find in SLS the edge e_j directly to the left of v_i
 - Connect v_i to helper(e_i)
 - \blacksquare helper(e_i) := v_i
 - Insert e into SLS
 - \blacksquare helper(e_i) := v_i



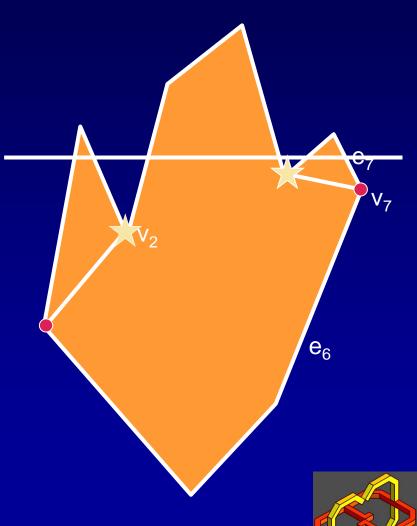
Merge Vertices

- \square Handling a *merge* vertex (v_i):
 - If helper(e_{i-1}) is a merge vertex, then connect v_i to helper(e_{i-1})
 - Remove e_{i-1} from SLS
 - Find in SLS the edge e_j directly to the left of v_i
 - If helper(e_j) is a merge vertex, then connect v_i to helper(e_i)
 - \blacksquare helper(e_i) := v_i



Regular Vertices

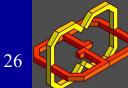
- \square Handling a *regular* vertex (v_i):
 - If the polygon's interior lies to the left of v_i then:
 - Find in SLS the edge e_j directly to the left of v_i
 - If helper(e_j) is a merge vertex, then connect v_i to helper(e_i)
 - \blacksquare helper(e_i) := v_i
 - Else:
 - If helper(e_{i-1}) is a merge vertex, then connect v_i to helper(e_{i-1})
 - Remove e_{i-1} from SLS
 - Insert e_i into SLS
 - \blacksquare helper(e_i) := v_i



Proof of Correctness: Split Vertices

 e_3

- \square Assume that the split vertex v_5 was connected to v_2 .
- \square Assume that $s=v_5v_2$ intersects another original edge e.
- \square Draw horizontal lines through v_5 and v_2 .
- □ Where can the endpoint of *e*, that is to the left of s, be?
 - Below l₁: Impossible. (Why?)
 - Between ℓ_1 and ℓ_2 : Ditto. (Why?)
 - Above ℓ_2 : Ditto. (Why?)
- Now assume that s intersects another diagonal. Why can't that be?
- Conclusion: Split events are resolved correctly.



 e_6

 e_9

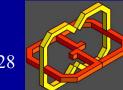
Proof of Correctness (cont.)

- Merge vertices: Exercise.
- Complete the details of the proof as an exercise.

Triangulating a y-monotone Polygon

In Theory

- Sweep the polygon from top to bottom.
- Greedily triangulate anything possible above the sweep line, and then forget about this region.
 - When we process a vertex *v*, the unhandled region above it always has a simple structure: Two y-monotone (left and right) chains, each containing at least one edge. If a chain consists of two or more edges, it is *reflex*, and the other chain consists of a single edge whose bottom endpoint has not been handled yet.
 - Each diagonal is added in O(1) time.



Triangulating a Y-monotone Polygon

In Practice

- Continue sweeping while one chain contains only one edge, while the other edge is concave.
- When a "convex edge" appears in the concave chain, triangulate as much as possible by connecting the new vertices to all visible vertices of the concave chain.



- When the edge in the other chain terminates, connect it to all the vertices of the concave chain using a "fan".
- Time complexity: O(k), where k is the complexity of the polygon.

Question: Why?!

Total Time-Complexity Analysis

Partitioning the polygon into monotone pieces:

 $O(n \log n)$

(every vertex event is handled in O(log *n*) time)

Triangulating all the monotone pieces: $\Theta(n)$

(every vertex event is handled in $\Theta(1)$ time)

 $O(n \log n)$ Total:

Historical Perspective

 $\bigcirc O(n^2) :$ Diagonal insertion

□ O(*n* log *n*): Lee and Preparata

(Monotone decomposition, 1977)

Avis and Toussaint (1981)

Chazelle (1982)

Optimal??

 \square O(n log log n): Tarjan and Van Wyk (1988)

 \bigcirc O($n \log^* n$): Randomized:

Clarkson, Tarjan, and Van Wyk (1989)

Seidel (Trapezoidal decomposition, 1991)

Devillers (1992)

Optimal (yet deterministic): \square $\Theta(n)$:

Chazelle (1991)

