

## 2-Point Site Voronoi Diagrams

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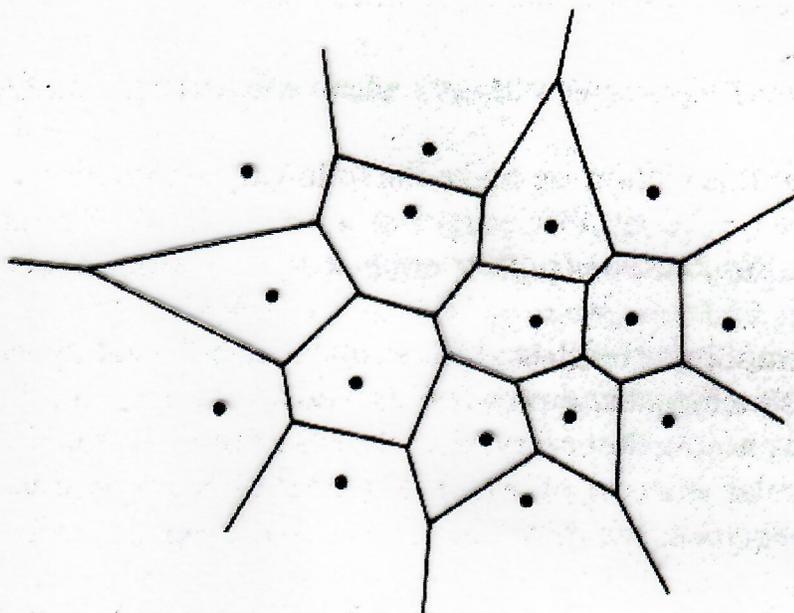
Middlebury  
College

Dartmouth  
College

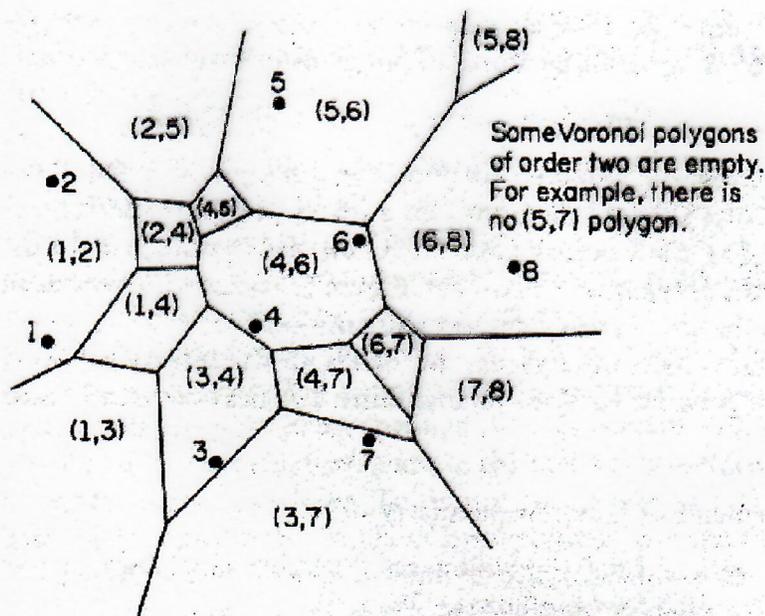


# Ordinary Voronoi Diagrams of Points in $\mathbb{R}^2$

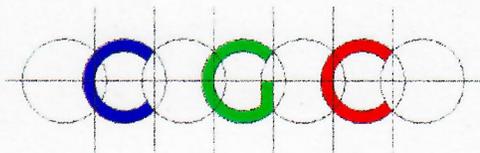
1st-order  
diagram



2nd-order  
diagram



(from [Preparata-Shamos 85, pp. 199, 235])



## 2-Site Distance Functions

1. **Sum of Distances:**

$$\mathcal{S}(v, (p, q)) = d(v, p) + d(v, q);$$

**Product of Distances:**

$$\mathcal{M}(v, (p, q)) = d(v, p) \cdot d(v, q).$$

2. **Triangle Area:**  $\mathcal{A}(v, (p, q)) = A(v, p, q).$

3. **Distance from a Line:**

$$\mathcal{L}(v, (p, q)) = \min_{u \in \ell_{pq}} d(v, u);$$

**Distance from a Segment:**

$$\mathcal{G}(v, (p, q)) = \min_{u \in \overline{pq}} d(v, u).$$

4. **Difference between Distances:**

$$\mathcal{D}(v, (p, q)) = |d(v, p) - d(v, q)|.$$

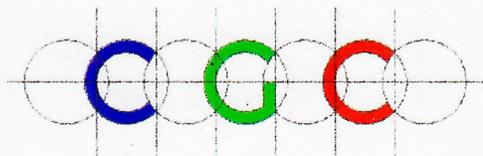
5. **Triangle Perimeter:**

$$\mathcal{P}(v, (p, q)) = d(p, q) + d(v, p) + d(v, q).$$

6. **Circumcircle Radius:**  $\mathcal{R}(v, (p, q)) =$

$$\frac{d(v, p)d(v, q)d(p, q)}{4\sqrt{s(s-d(v, p))(s-d(v, q))(s-d(p, q))}},$$

where  $s = \mathcal{P}(v, (p, q))/2.$



## Results (worst-case diagram complexities)

$\mathcal{F}$	$ V_{\mathcal{F}}^{(N)}(S) $ (NN Diagram)	$ V_{\mathcal{F}}^{(F)}(S) $ (FN Diagram)
$\mathcal{S}, \mathcal{M}$	$\Theta(n)^*$	$\Theta(n)$
$\mathcal{A}$	$\Theta(n^4)^*$	$\Theta(n^2)$
$\mathcal{L}$	$\Theta(n^4)^*$	$\Theta(n^2)$
$\mathcal{G}$	$\Theta(n^4)^*$	$\Theta(n)$
$\mathcal{D}$	$\Omega(n^4)^*, O(n^{4+\varepsilon})$	$\Theta(n^2)$
$\mathcal{P}$	?	?
$\mathcal{R}$	?	?

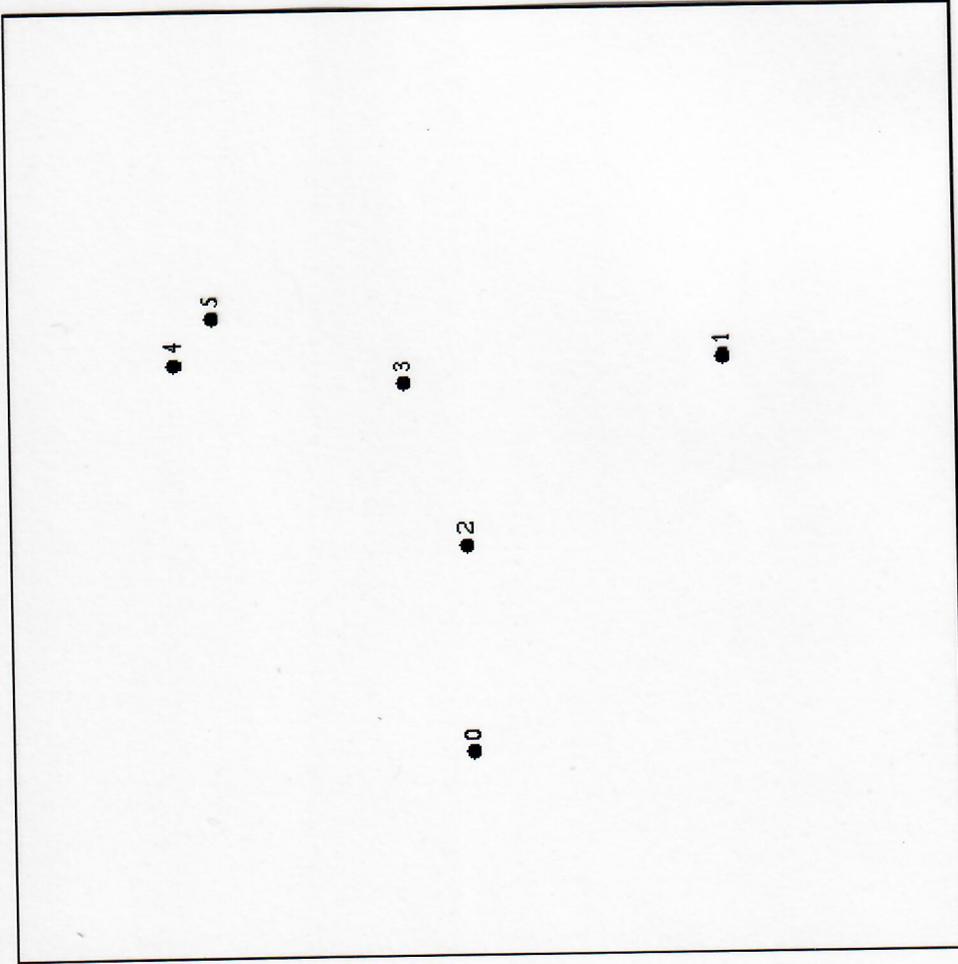
\* Always

Legend:

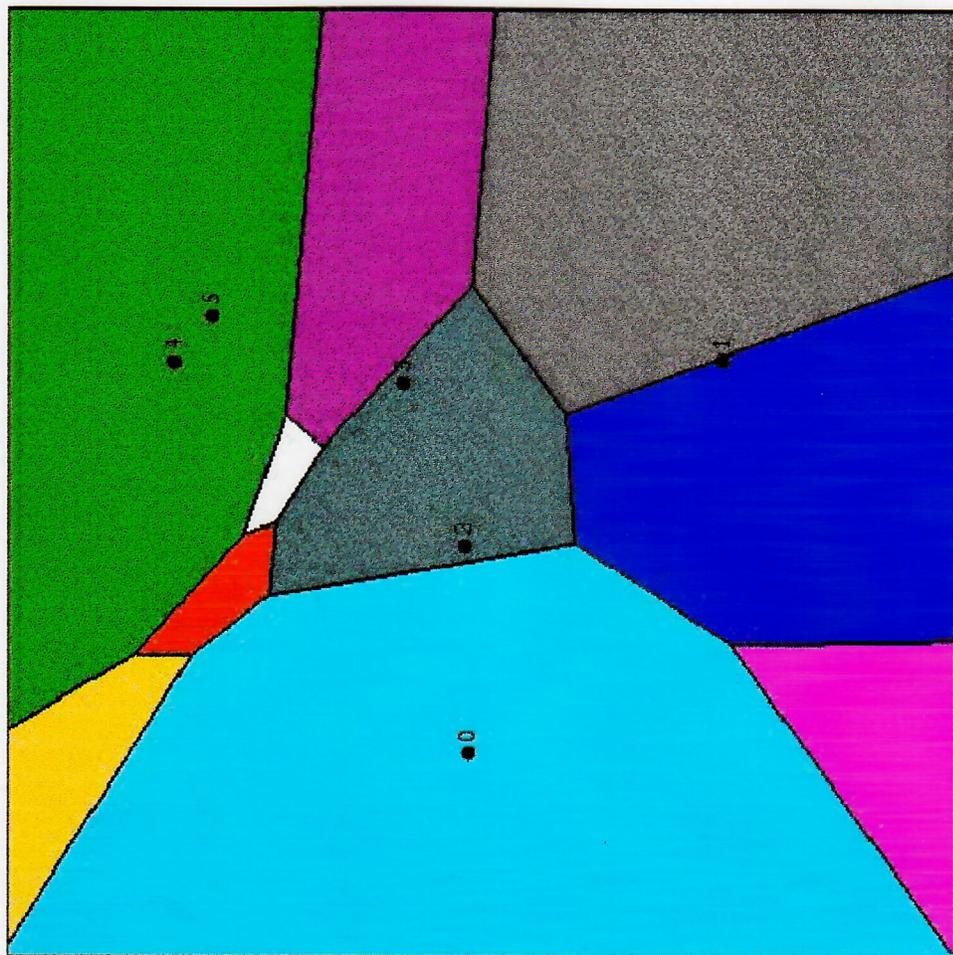
$S$ : a set of  $n$  points in  $\mathbb{R}^2$ ;

$V_{\mathcal{F}}^{(N|F)}(S)$ : Nearest/furthest-neighbor  
Voronoi diagram w.r.t.  $\mathcal{F}$ .





**Point set**



1	2	3	4	5	2	3	4	5	3	4	5	4	5	5	5
0	0	0	0	0	1	1	1	1	2	2	2	3	3	4	4
■	■	■	■	■	■	■	■	■	■	■	■	■	■	■	■

**Sum (or product) of distances: NN Voronoi**

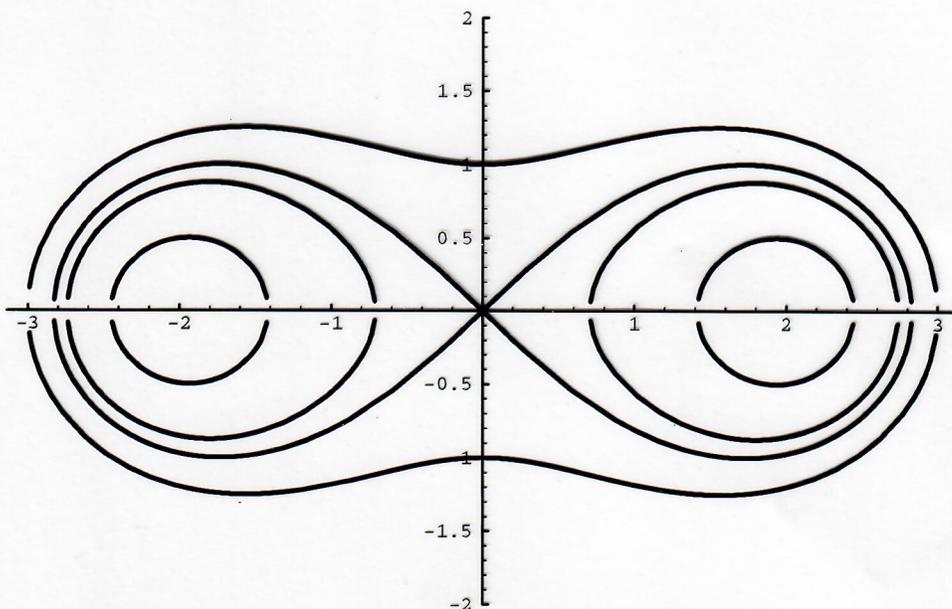


## Sum and Product of Distances

Growing shape:

Sum: an ellipse;

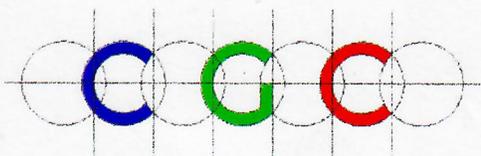
Product: a pair of leaves.

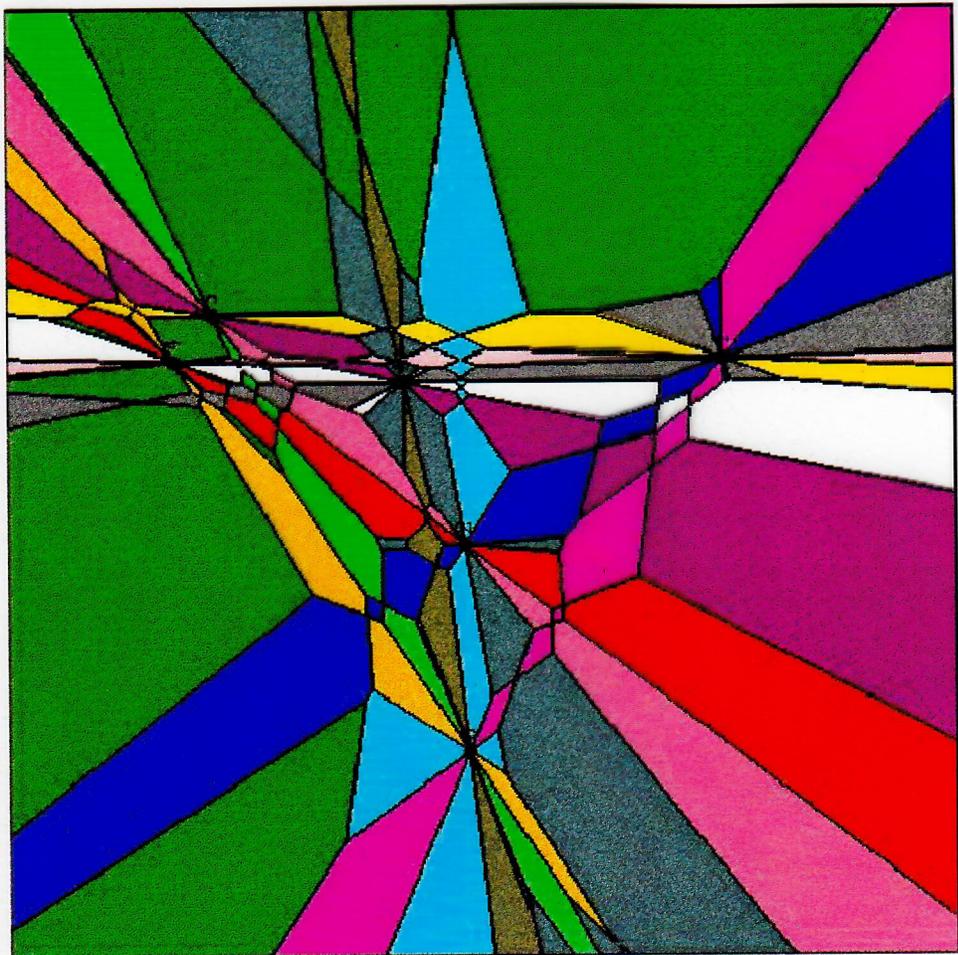


Theorem:

$V_{\mathcal{S}|\mathcal{M}}^{(N|F)}(S)$  are identical to the regular (one-site, Euclidean metric) 2nd-order  $V^{(N|F)}(S)$ .

(Therefore  $|V_{\mathcal{S}|\mathcal{M}}^{(N|F)}(S)| = \Theta(n)$ .)





1	2	3	4	5	2	3	4	5	3	4	5	4	5	5
0	0	0	0	0	1	1	1	1	2	2	2	3	3	4

**Triangle area: NN Voronoi diag.**

## Triangle Area

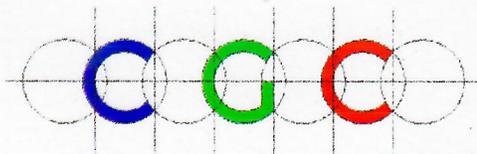
Growing shape: an infinite strip; speed inversely-proportional to  $d(p, q)$ .

Theorem:  $|V_{\mathcal{A}}^{(N)}(S)| = \Theta(n^4)$ .

Proof:

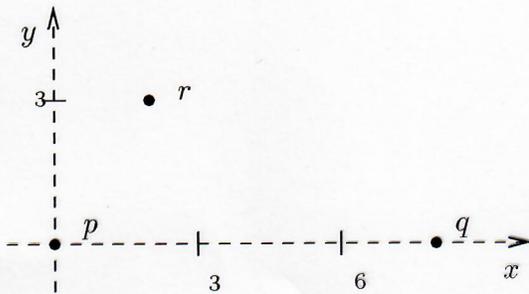
Lower bound:  $\Theta(n^4)$  intersection points of lines.

Upper bound: using the zone theorem [Edel.-Seidel-Sharir 93].

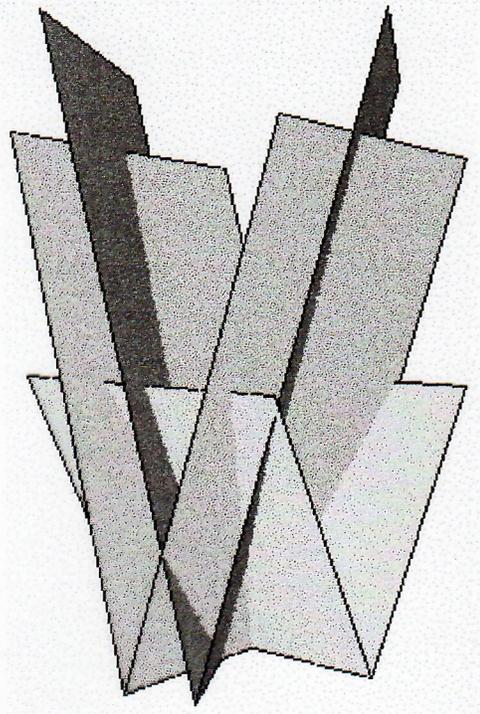


# Triangle Area (cont.)

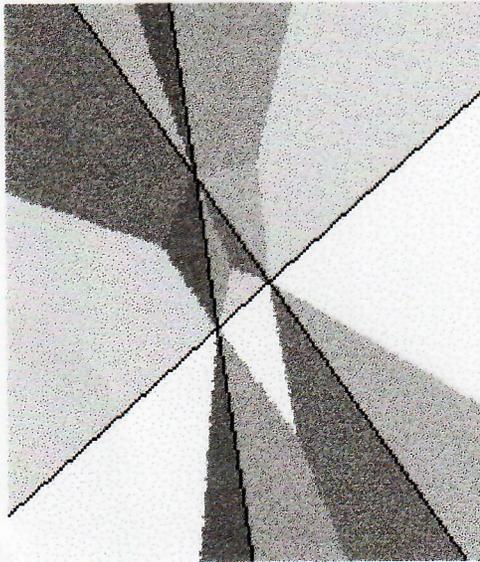
Computing  $V_{\mathcal{A}}$ :



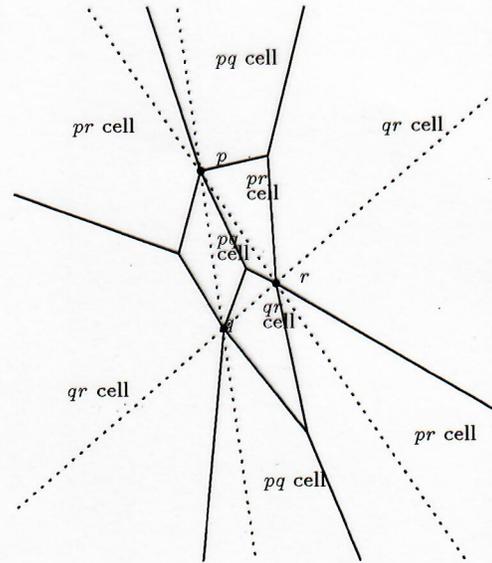
(a) Point set



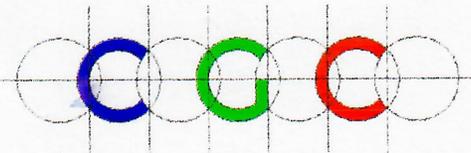
(b) Surfaces

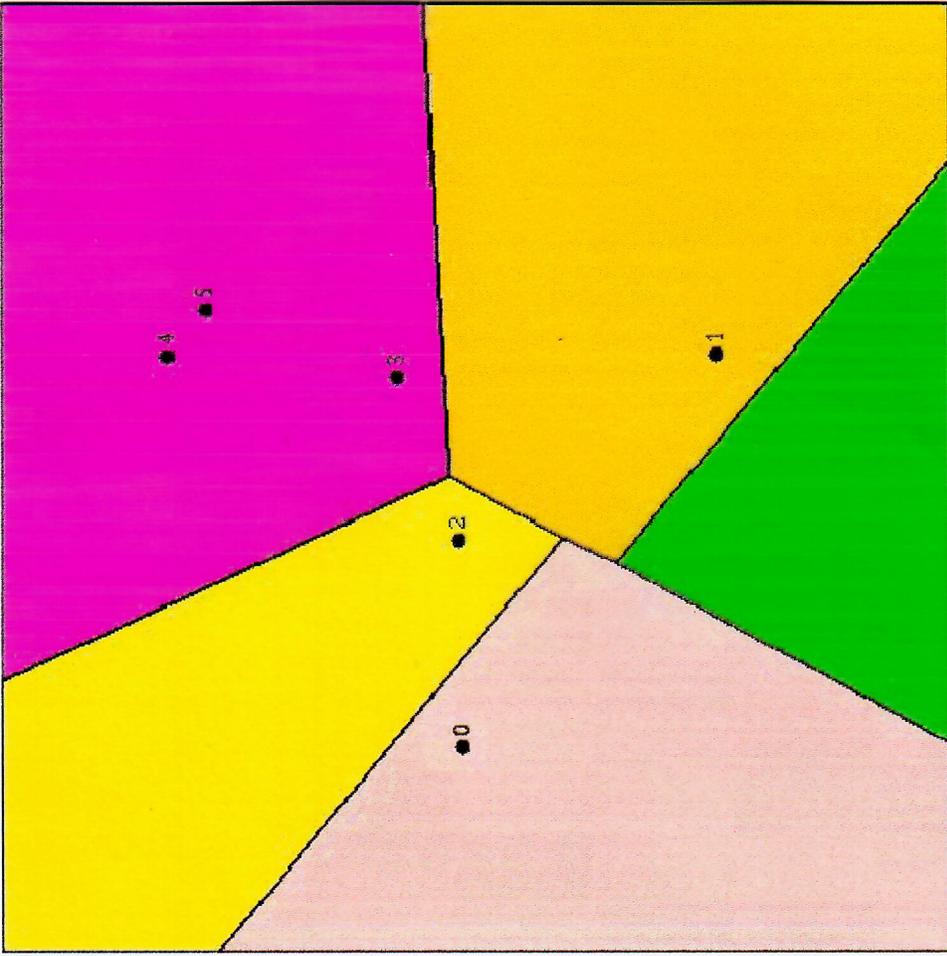
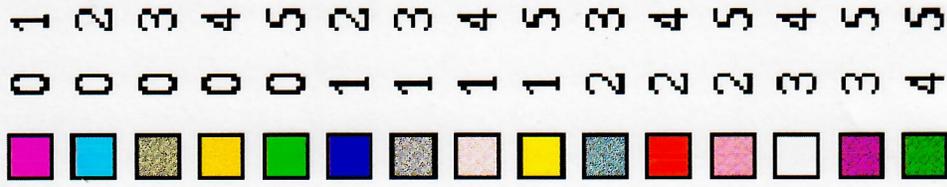


(c) Lower envelope



(d) Voronoi diagram





**Triangle area: FN Voronoi diag.**

## Triangle Area (cont.)

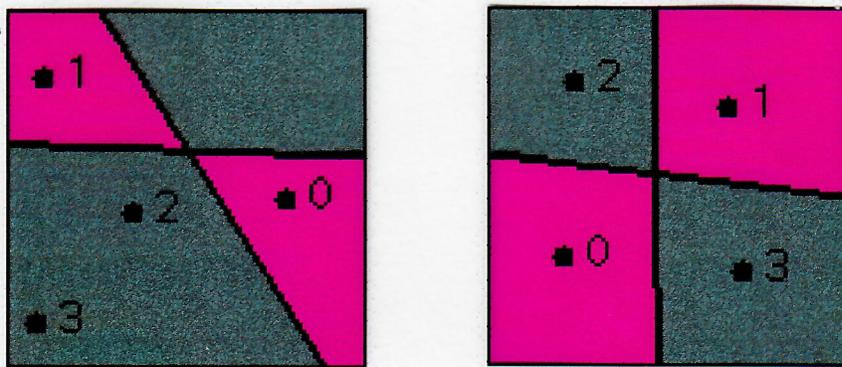
Theorem:  $|V_{\mathcal{A}}^{(F)}(S)| = \Theta(n^2)$ .

Proof:

Lower bound: by example.

Upper bound:

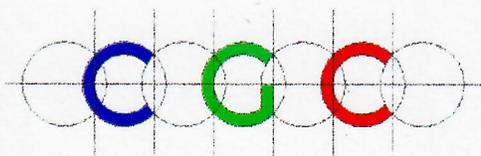
each region has  $\leq 2$  convex cells; also:  
upper envelope of an arrangement of  $\Theta(n^2)$   
planes in  $\mathbb{R}^3$  (using [Sharir-Agarwal 95]).



$(0,1)-(2,3)$  bisector

Theorem:

$V_{\mathcal{A}}^{(N|F)}(S)$  can be computed in  $O(n^{4|2} \log n)$   
time and  $O(n^{4|2})$  space. (By a divide-and-  
conquer lower-envelope algorithm.)

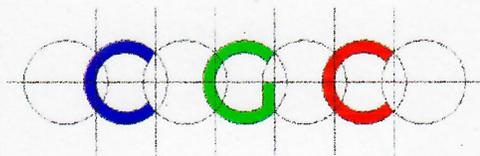
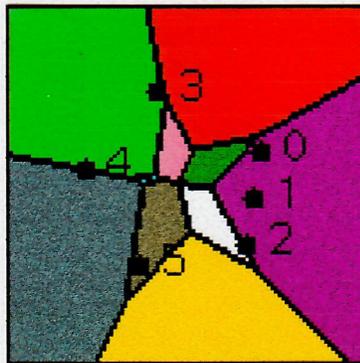


## Triangle Area (cont.)

Theorem:

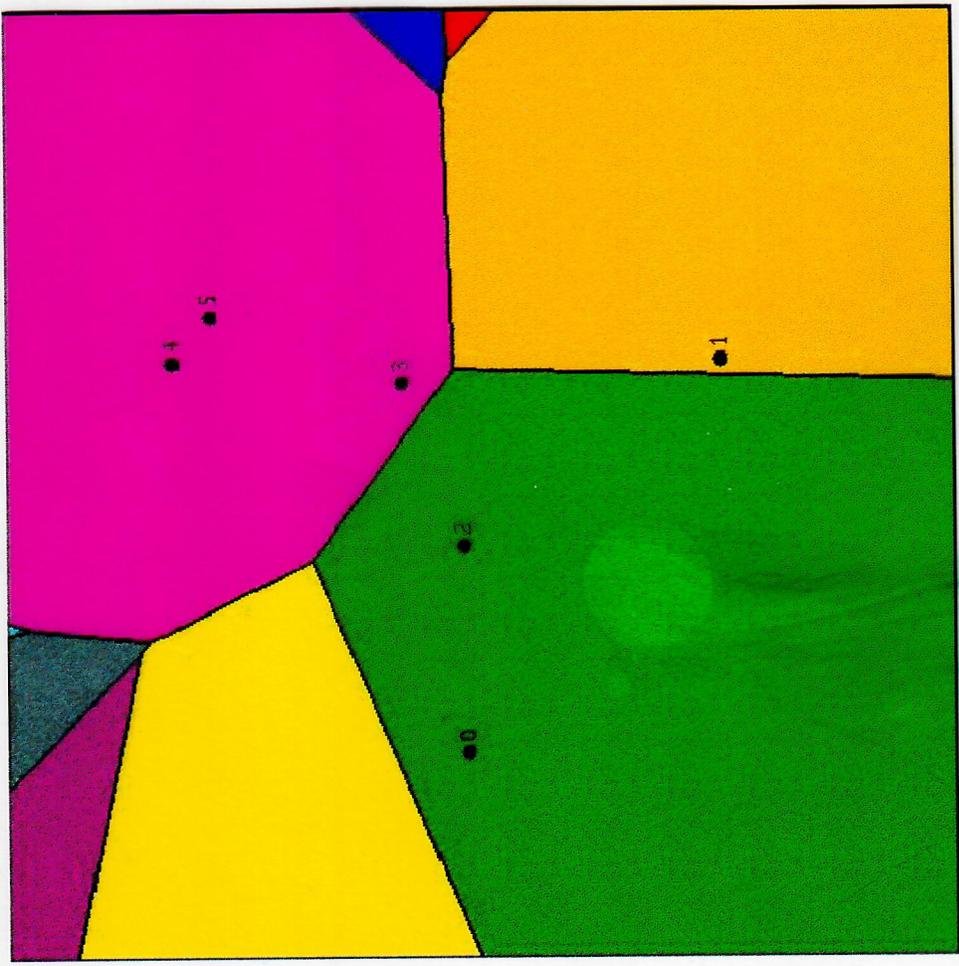
In  $V_A^{(F)}(S)$ :

1. Only hull points (not on a hull edge) have non-empty regions.
2. Only antipodal points have infinite cells.





- 0 1
- 0 2
- 0 3
- 0 4
- 0 5
- 1 2
- 1 3
- 1 4
- 1 5
- 2 3
- 2 4
- 2 5
- 3 4
- 3 5
- 4 5



**Distance from a line: FN Voronoi diag.**

## Distance from a Line

Growing shape: a strip.

Theorem:

$$|V_{\mathcal{L}}^{(N)}(S)| = \Theta(n^4) \text{ and } |V_{\mathcal{L}}^{(F)}(S)| = \Theta(n^2).$$

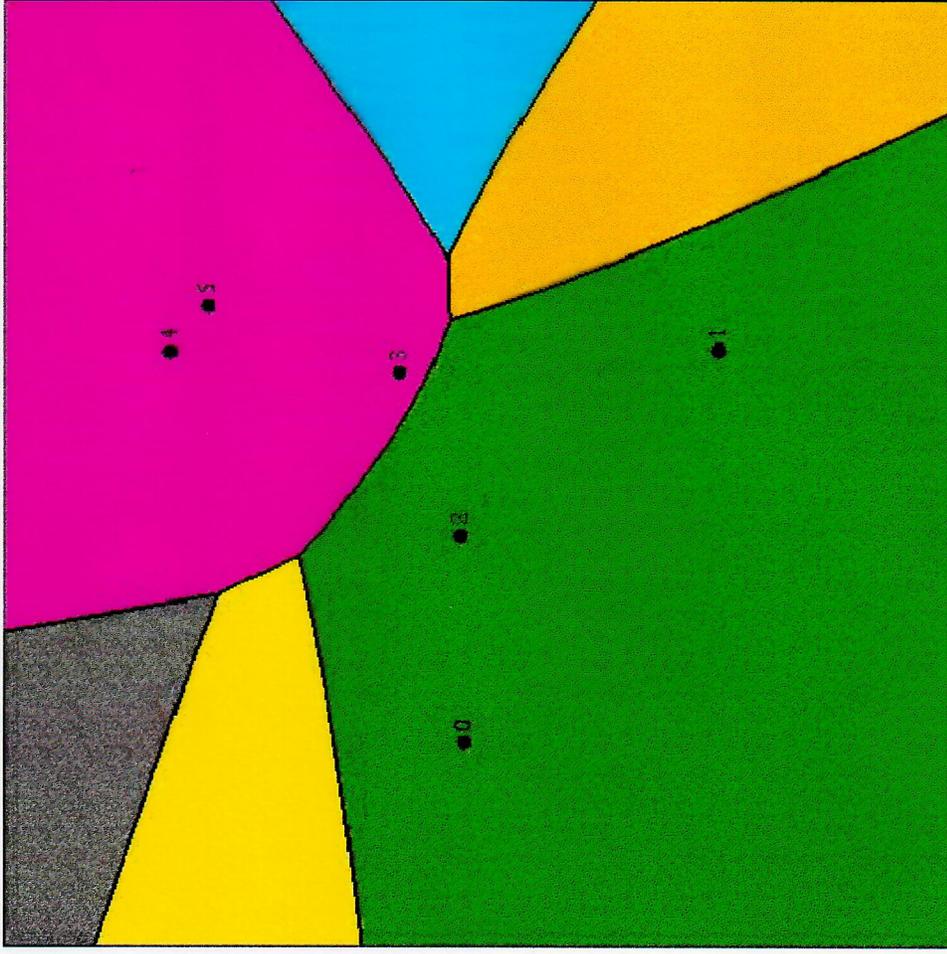
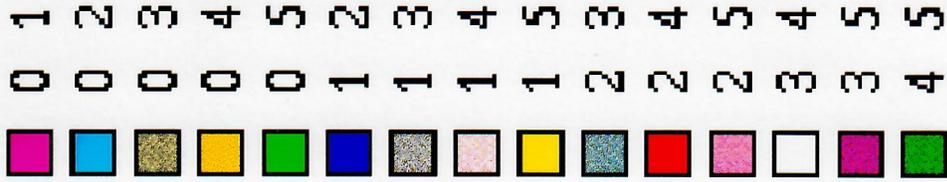
Proof:

Same as for the triangle-area function.

(All the half-planes now have slope  $\pi/4$ .)







**Distance from a segment: FN Voronoi diag.**

## Distance from a Segment

Growing shape: a hippodrome.

Theorem:  $|V_{\mathcal{G}}^{(N)}(S)| = \Theta(n^4)$ .

Proof:

Lower bound:  $\Theta(n^4)$  segment-intersection points (using [Leighton 83]).

Upper bound: by splitting segments (using [Lee-Drysdale 81]).

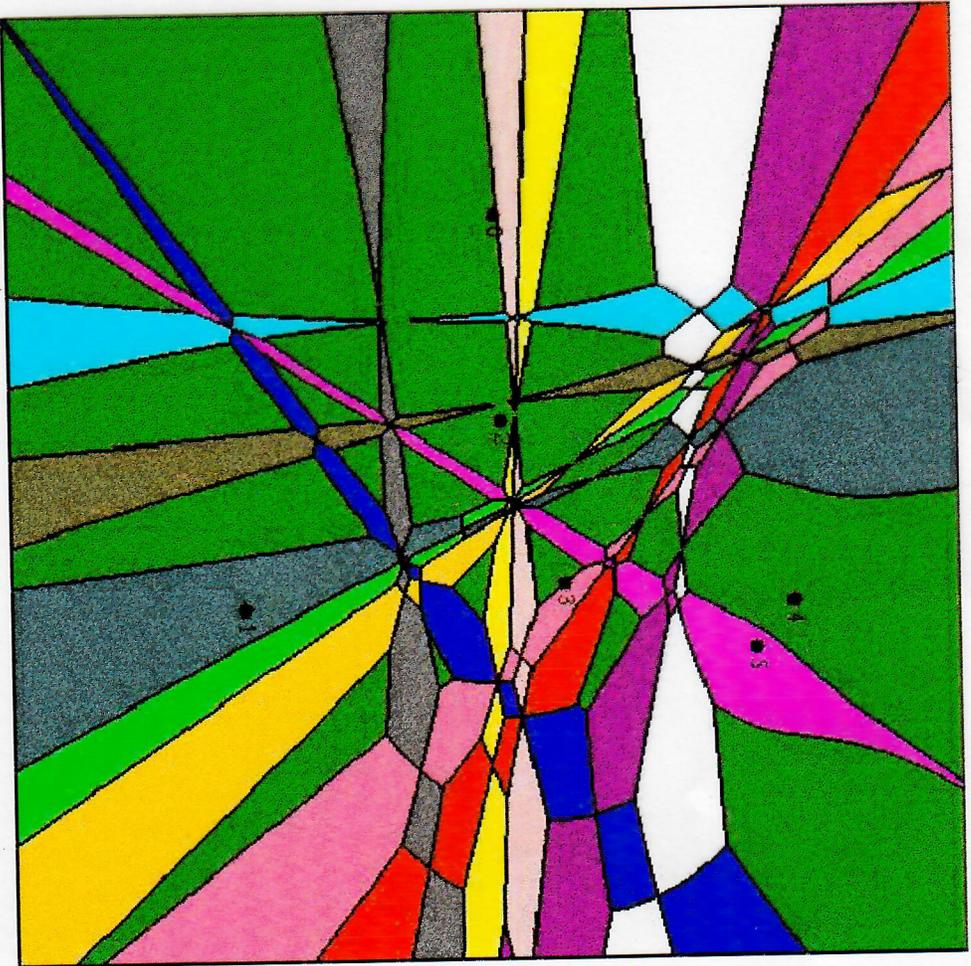
Theorem:  $|V_{\mathcal{G}}^{(F)}(S)| = \Theta(n)$ .

Proof: By “merging” the outer and inner convex hulls:  $\text{CH}(S)$  and  $\text{CH}(S \setminus \text{CH}(S))$ .

Theorem:  $V_{\mathcal{G}}^{(N)}(S)$  can be computed in  $O(n^4 \log n)$  time and  $O(n^4)$  space. (By either the D&C envelope algorithm, or by algorithms of [Fortune 86] and [Yap 87].)

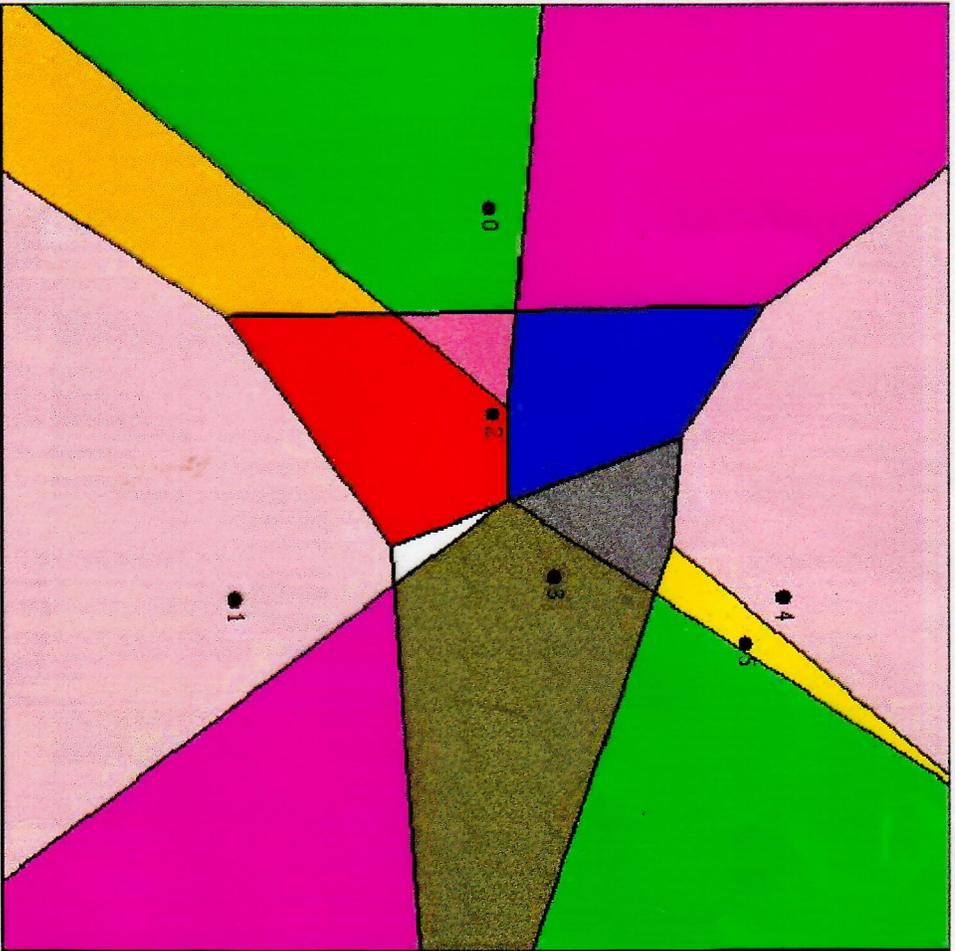


■	0	1
■	0	2
■	0	3
■	0	4
■	0	5
■	1	3
■	1	4
■	1	5
■	2	3
■	2	4
■	2	5
■	3	4
■	3	5
■	4	5



**Difference of distances: NN Voronoi diag.**

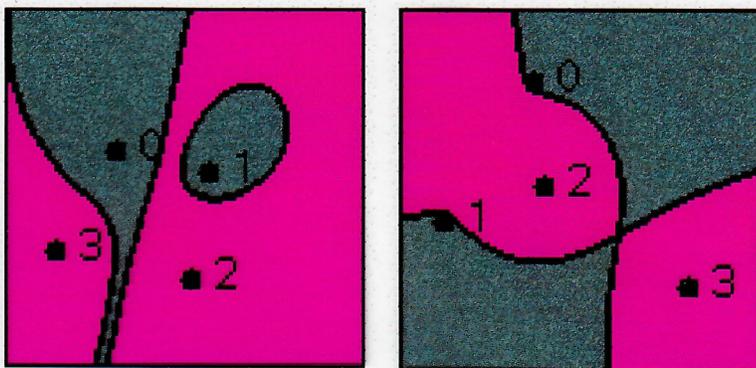
■	0	1
■	0	2
■	0	3
■	0	4
■	0	5
■	1	2
■	1	3
■	1	4
■	1	5
■	2	3
■	2	4
■	2	5
■	3	4
■	3	5
■	4	5



**Difference of distances: FN Voronoi diag.**

## Difference between Distances

Growing shape: a “strip” bounded by two hyperbolas.



(0,1)–(2,3) bisector

Theorem:  $V_{\mathcal{D}}^{(N)}(S) = \Omega(n^4), O(n^{4+\varepsilon})$ .

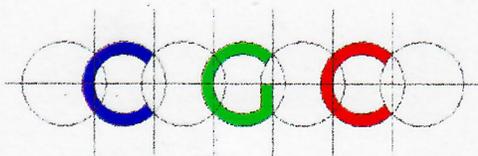
Proof:

Lower bound:  $\Theta(n^4)$  intersection points  
between segment bisectors.

Upper bound: lower envelope of algebraic  
surfaces of constant degree  
[Sharir-Agarwal 95].

Theorem:  $V_{\mathcal{D}}^{(F)}(S) = \Theta(n^2)$ .

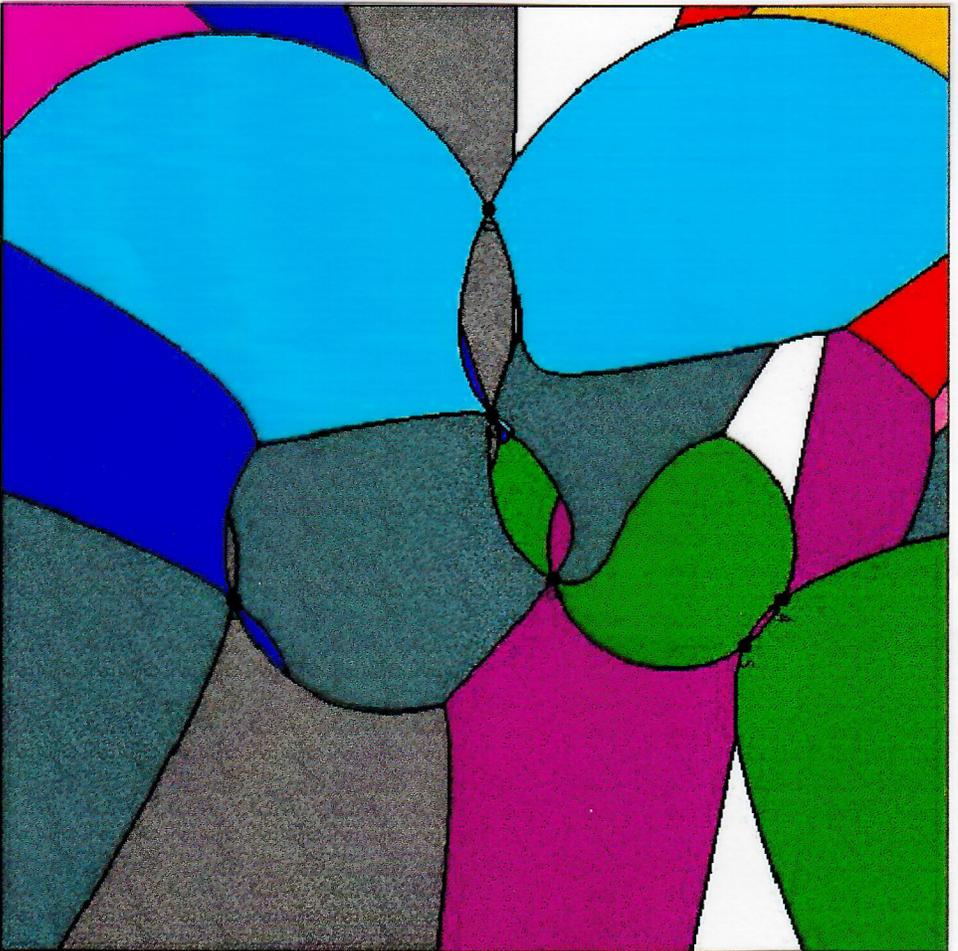
Proof: Overlay of the regular  $V^{(N|F)}(S)$ .







■	0	1
■	0	2
■	0	3
■	0	4
■	0	5
■	1	2
■	1	3
■	1	4
■	1	5
■	2	3
■	2	4
■	2	5
■	3	4
■	3	5
■	4	5



**Circumcircle radius: NN Voronoi diag.**





## Java Applet

Implementing bisector/NN/FN for all the discussed distance functions.

Look at:

`http://www.middlebury.edu/  
~dickerso/research/dfunct.html`

or

`http://www.cgc.cs.jhu.edu/  
~barequet/2-point.html`

